

EECS 373

Design of Microprocessor-Based Systems

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Lecture 6: Memory-mapped I/O review, APB, start interrupts.

24 January 2017

Slides inherited from Mark Brehob.

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Outline

- [Lecture flow](#)
- Context and review
- Tuesday lab
- Assembler directives
- Hardware vs. software programming
- APB
- Caller/callee saved registers review
- Volatile keyword
- Pointers and function pointers
- Weak references
- Interrupts



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Lecture flow



- Feedback: Not always clear why we are learning particular material, and jumping from topic to topic can make this worse.
- Resolutions:
 - Explain reason for each topic at transitions.
 - Context and review at start of each lecture.
- Keep on giving feedback.
 - Teaching the way I would learn best doesn't work.
 - I learn is a weird way.
- I really do act on the feedback.

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Context and review



- Just finished memory-mapped IO.
 - Write and read memory locations to trigger actions by peripherals.
- Approaches to design and debugging
 - Graph model
 - Get a simple version working
- Using stack in parameter passing.
- Project problem selection.
 - Were the small group meetings helpful?
 - Will require two short project proposals soon.
- Started on APB
 - Did a simple example.
 - Will do a more complex example today.

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Tuesday lab



- Before lecture.
- I have been watching this and covering essential material previous Thursday.
- However, I will often have reinforcing or more detailed examples on Tuesday.
- When labs are all done, will compare lab medians for Tuesday lab and rest of class.
- If there is a significant difference, will adjust Tuesday lab grades.
- Don't expect a significant difference.
- Lab staff know their stuff.
- Do generally cover the essentials first.

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Assembler directives



- Reason for covering: Some people were confused about this in lab.
- Assembler directions don't necessary generate any instructions.
- Convenience to allow more modular and organized code, e.g., `.equ`.
- Generates no code.
- Acts like a preprocessor macro (`#define`) in C.
- Provide information about data to include, e.g., `.word`.
- Tell assembler which symbols are global, e.g., `.global`.
- Indicate where in memory things (code and data) should sit, e.g., `.text`

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Assembler directives example



```
@ "#define"-like
.equ  STACK_TOP, 0x20000800
.equ  SYSREG_SOFT_RST_CR, 0xE0042030

@ Make _start externally visible (to ld).
.global _start

@ "a": allocatable
@ %progbits: section contains data
@ .int_vector: section name. link.ld uses this.
.section .int_vector, "a", %progbits

_start:
    .word  STACK_TOP, main
```

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Hardware vs. software programming



- Reasons covering
 - Common sticking point
 - A few students have had trouble with this in lab
- HDL → FPGA
 - Control which functions (gates) are implemented.
 - Control how they are connected.
- Assembly/C → ARM Cortex M-3
 - Control instruction sequences.
 - Control data to load into memory before execution.

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Outline



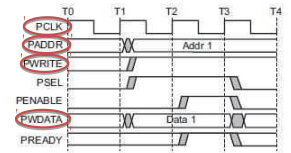
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APB bus signals



- PCLK
 - Clock
- PADDR
 - Address on bus
- PWRITE
 - 1=Write, 0=Read
- PWDATA
 - Data written to the I/O device. Supplied by the bus master/processor.

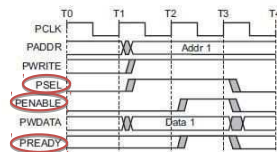


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APB bus signals

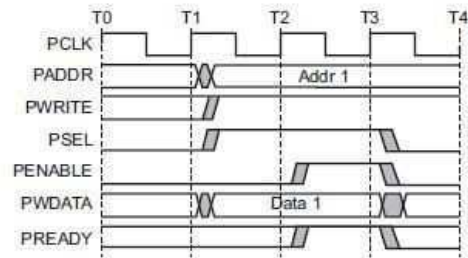


- PSEL
 - Asserted if the current transaction is targeted *this* device
- PENABLE
 - High during entire transaction *other than* the first cycle.
- PREADY
 - Driven by target. Similar to our #ACK. Indicates if the target is *ready* to do transaction.
 - Each target has its own PREADY



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So what's happening here?



Example setup

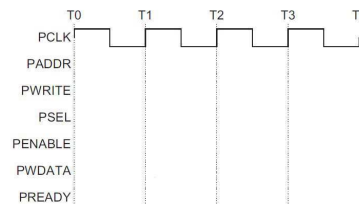


- For the next couple of slides, we will assume we have one bus master "CPU" and two slave devices (D1 and D2)
- D1 is mapped to address
 - 0x00001000-0x0000100F
 - D2 is mapped to addresses
 - 0x00001010-0x0000101F

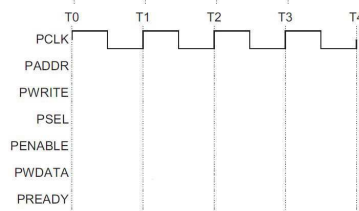
Say the CPU does a store to location 0x00001004 with no stalls



D1



D2

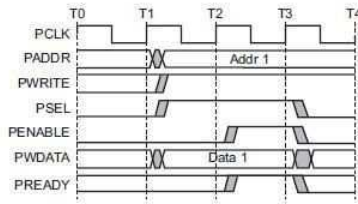


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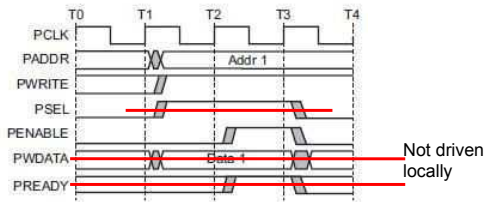
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D1

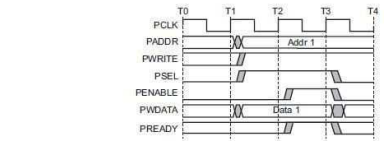
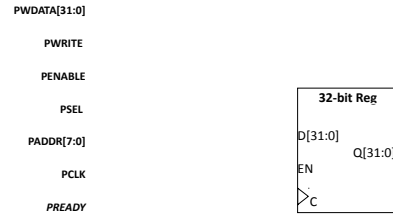


D2



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What if we want to have the LSB of this register control an LED?



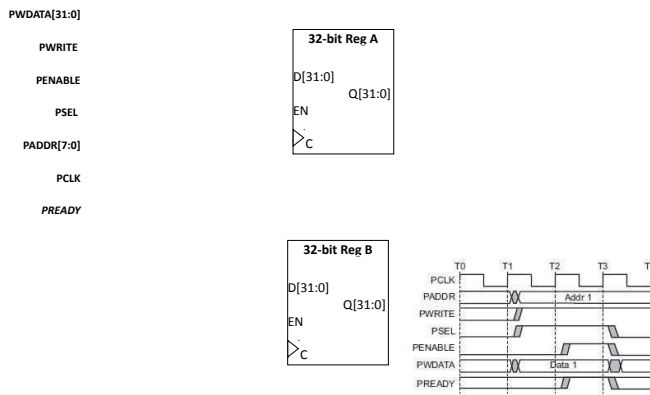
We are assuming APB only gets lowest 8 bits of address here...

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Reg A should be written at address 0x00001000
Reg B should be written at address 0x00001004

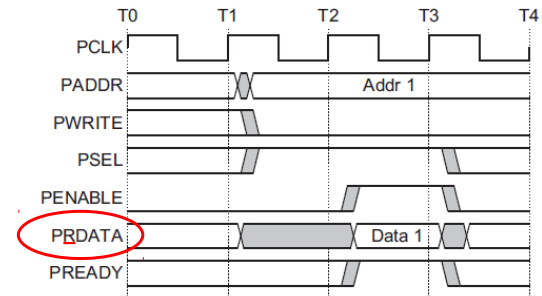


Reads...



We are assuming APB only gets lowest 8 bits of address here...

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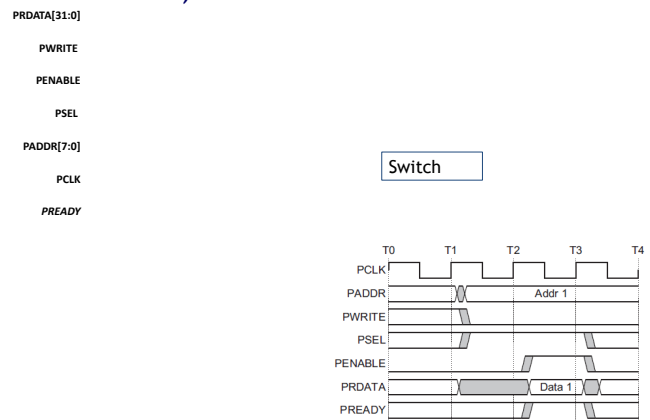
Each slave device has its own local PRDATA bus.

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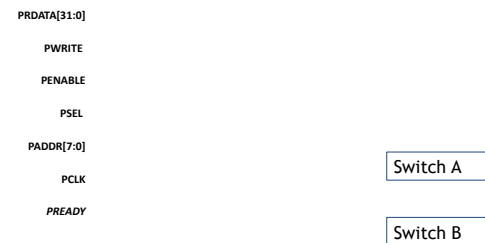
Let's say we want a device that provides data from a switch on a read to any address it is assigned.
(so returns a 0 or 1)



Device provides data from switch A if address 0x00001000 is read from. B if address 0x00001004 is read from

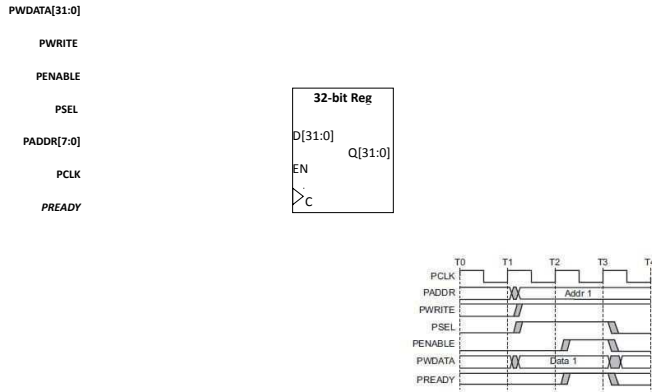


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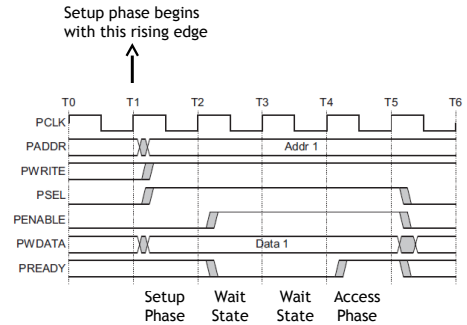
All reads read from register, all writes write...



We are assuming APB only gets lowest 8 bits of address here...

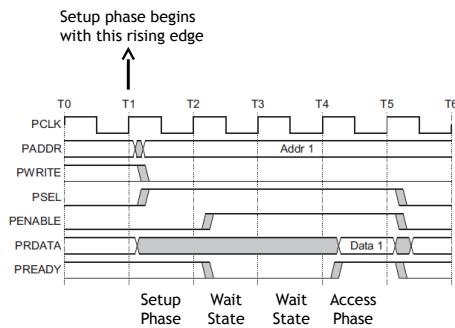
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A write transfer with wait states



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A read transfer with wait states



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Errors and stalling



- There is another signal, PSLVERR (APB Slave Error) which we can drive high if things go bad.
 - Nothing will go wrong with our device: ground it.
- Notice we are assuming that our device need not stall.
 - Could stall if we needed.
 - If you need more than a few extra cycles, generally means your design should change.

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Verilog



```

/** APB3 BUS INTERFACE **/
input PCLK,           // clock
input PREGERN,        // system reset
input PSEL,           // peripheral select
input PENABLE,        // distinguishes access phase
output wire PREADY,   // peripheral ready signal
output wire PSLVERR,  // error signal
input PWRITE,         // distinguishes read and write cycles
input [31:0] PADDR,   // I/O address
input wire [31:0] PWDATA, // data from processor to I/O device (32 bits)
output reg [31:0] PRDATA, // data to processor from I/O device (32-bits)

/** I/O PORTS DECLARATION **/
output reg LEDOUT, // port to LED
input SW,          // port to switch
};

assign PSLVERR = 0;
assign PREADY = 1;

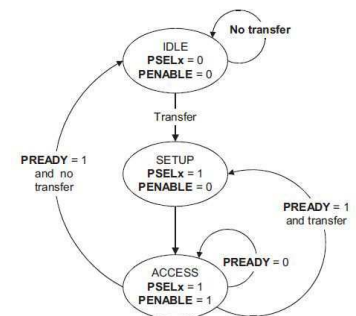
```

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APB state machine



- IDLE
 - Default APB state
- SETUP
 - When transfer required
 - PSELx is asserted
 - Only one cycle
- ACCESS
 - PENABLE is asserted
 - Addr, write, select, and write data remain stable
 - Stay if PREADY = L
 - Goto IDLE if PREADY = H and no more data
 - Goto SETUP is PREADY = H and more data pending



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Caller/callee saved registers review



Reason for covering: Some people didn't understand this and it is important for the project.

Some code

function_call()

- This can walk all over r0-r3.
- If this ends up needing a veneer, the linker might insert code clobbering r12.
- Preserve r0-r3 and r12 if we'll read before write after the call.

More code

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Caller/callee saved registers review



Reason for covering: Some people didn't understand this and it is important for the project.

Was just called

- I'm allowed to clobber r0-r3.
- Safe to clobber r12, too, because linker may have already clobbered it.
- Not worrying about special registers >r12.
- Need to save/restore everything else if it will be written: r5-r11

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Volatile keyword



Reason for covering: You need this to safely write C code that plays with IO devices.

Definition: this value may be changed by something outside this program.

Examples

- `#define LED_ADDR ((volatile const unsigned *) (8))`
- `volatile const unsigned *led_addr = 0x8;`

Otherwise, compiler might optimize away actual memory accesses.

What's volatile? The pointer or the value pointed to?

<http://cdecl.org> is great!

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Pointers and function pointers



- Reason for covering: Function pointers let you essentially pass code around dynamically among functions and build vector tables in C.
- Pointers
 - Type-safe addresses.
 - Avoid void * unless really needed.
 - When would you use this?
 - The type of the object cannot be known at compile time.

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Function pointers



```
// Can use for generic functions.
int apple_checker(const void *x);

int orange_checker(const void *x);

int check_stuff(void *stuff_array,
    int (*checker)(const void *));

// Can use for jump tables.
void (*func_ptr[3]) = {func1, func2, func3};
```

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Weak references



- Reason for covering: A trick to conditionally call functions that may be useful in Lab 4 and your projects.

What does a weak symbol imply?

- Provides a default entry in a function vector.
- Why useful? Allows override at link time.

What does a call through a weak symbol imply?

- If the symbol exists, call the function.
- If not, do nothing.
- Why useful? Allows link-time conditional calls without recompilation.
- Especially useful for large projects using libraries and multiple build versions.

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Void *, a short illustrative script



Compiler: Excuse me, sir. May I suggest using a round peg?

Programmer: Shut up! I don't care! Just do it!

Compiler: As you wish, sir.

OS: Where would you like your 10GB core dump file delivered?

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- **Interrupts**

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Interrupts



Merriam-Webster:

- “to break the uniformity or continuity of”

- Informs a program of some external events
- Breaks execution flow

Key questions:

- Where do interrupts come from?
- How do we save state for later continuation?
- How can we ignore interrupts?
- How can we prioritize interrupts?
- How can we share interrupts?

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I/O Data Transfer



Two key questions to determine how data is transferred to/from a non-trivial I/O device:

1. How does the CPU know when data is available?
 - a. Polling
 - b. Interrupts
2. How is data transferred into and out of the device?
 - a. Programmed I/O
 - b. Direct Memory Access (DMA)

Interrupts



Interrupt (a.k.a. exception or trap):

- Makes CPU stop executing the current program and begin executing a an **interrupt handler** or **interrupt service routine (ISR)**. ISR does something and allows program to resume.

Similar to procedure calls, but

- **can occur between any two instructions**
- are transparent to the running program (usually)
- are not generally explicitly called by program
- call a procedure at an address determined by the type of interrupt, not the program

Two types of interrupts



- Those caused by an instruction
 - Examples:
 - TLB miss
 - Illegal/unimplemented instruction
 - div by 0
 - Names:
 - Trap, exception

Two basic types of interrupts



- Those caused by the external world
 - External device
 - Reset button
 - Timer expires
 - Power failure
 - System error
- Names:
 - interrupt, external interrupt

How it works



- Something tells the processor core there is an interrupt
- Core transfers control to code that needs to be executed
- Said code “returns” to old program
- Much harder then it looks.
 - Why?

Details



- How do you figure out *where* to branch to?
- How do you ensure that you can get back to where you started?
- Don't we have a pipeline? What about partially executed instructions?
- What if we get an interrupt while we are processing our interrupt?
- What if we are in a "critical section?"

Where



- If you know *what* caused the interrupt then you want to jump to the code that handles that interrupt.
 - If you number the possible interrupt cases, and an interrupt comes in, you can just branch to a location, using that number as an offset (this is a branch table)
 - If you don't have the number, you need to *poll* all possible sources of the interrupt to see who caused it.
 - Then you branch to the right code
 - Ugly.

Get back to where you once belonged



- Need to store the return address somewhere.
 - Stack *might* be a scary place.
 - *That* would involve a load/store and might cause an interrupt (page fault)!
 - So a dedicated register seems like a good choice
 - But that might cause problems later...

Snazzy architectures



- A modern processor has *many* instructions in-flight at once.
 - What do we do with them?
- Drain the pipeline?
 - What if one of them causes an exception?
- Squash them all and restart later
 - Slows
- What if the instruction that caused the exception was executed before some other instruction?
 - What if that other instruction caused an interrupt?

Nested interrupts



- If we get one interrupt while handling another what to do?
 - Just handle it
 - But what about that dedicated register?
 - What if I'm doing something that can't be stopped?
 - Ignore it
 - But what if it is important?
 - Prioritize
 - Take those interrupts you care about.
 - Ignore the rest.
 - Still have dedicated register problems.

Critical section



- We probably need to ignore some interrupts but take others.
 - Probably should be sure *our* code can't cause an exception.
 - Use same prioritization as before.

Our processor



- Over 100 interrupt sources
 - Power on reset, bus errors, I/O pins changing state, data in on a serial bus etc.
- Need a great deal of control
 - Ability to enable and disable interrupt sources
 - Ability to control where to branch to for each interrupt
 - Ability to set interrupt priorities
 - Who wins in case of a tie
 - Can interrupt A interrupt the ISR for interrupt B?
 - If so, A can “preempt” B.
- All that control will involve memory mapped I/O.
 - And given the number of interrupts that’s going to be a pain.

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Enabling and disabling interrupt sources

- Interrupt Set Enable and Clear Enable
 - 0xE000E100-0xE000E11C, 0xE000E180-0xE000E19C

0xE000E100	SETENA0	R/W	0	Enable for external interrupt #0-31 bit[0] for interrupt #0 (exception #16) bit[1] for interrupt #1 (exception #17) ... bit[31] for interrupt #31 (exception #47) Write 1 to set bit to 1; write 0 has no effect Read value indicates the current status
0xE000E180	CLRENA0	R/W	0	Clear enable for external interrupt #0-31 bit[0] for interrupt #0 bit[1] for interrupt #1 ... bit[31] for interrupt #31 Write 1 to clear bit to 0; write 0 has no effect Read value indicates the current enable status

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How to know where to go on an interrupt.



```

239 pfnVectors:
24   .word _estack
25   .word Reset_Handler
26   .word NMI_Handler
27   .word HardFault_Handler
28   .word MemManage_Handler
29   .word BusFault_Handler
30   .word UsageFault_Handler
31   .word 0
32   .word 0
33   .word 0

```

```

192 /=====
193 * Reset_Handler
194 */
195 .global Reset_Handler
196 .type Reset_Handler, %function
197 Reset_Handler:
198 _start:

```

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