

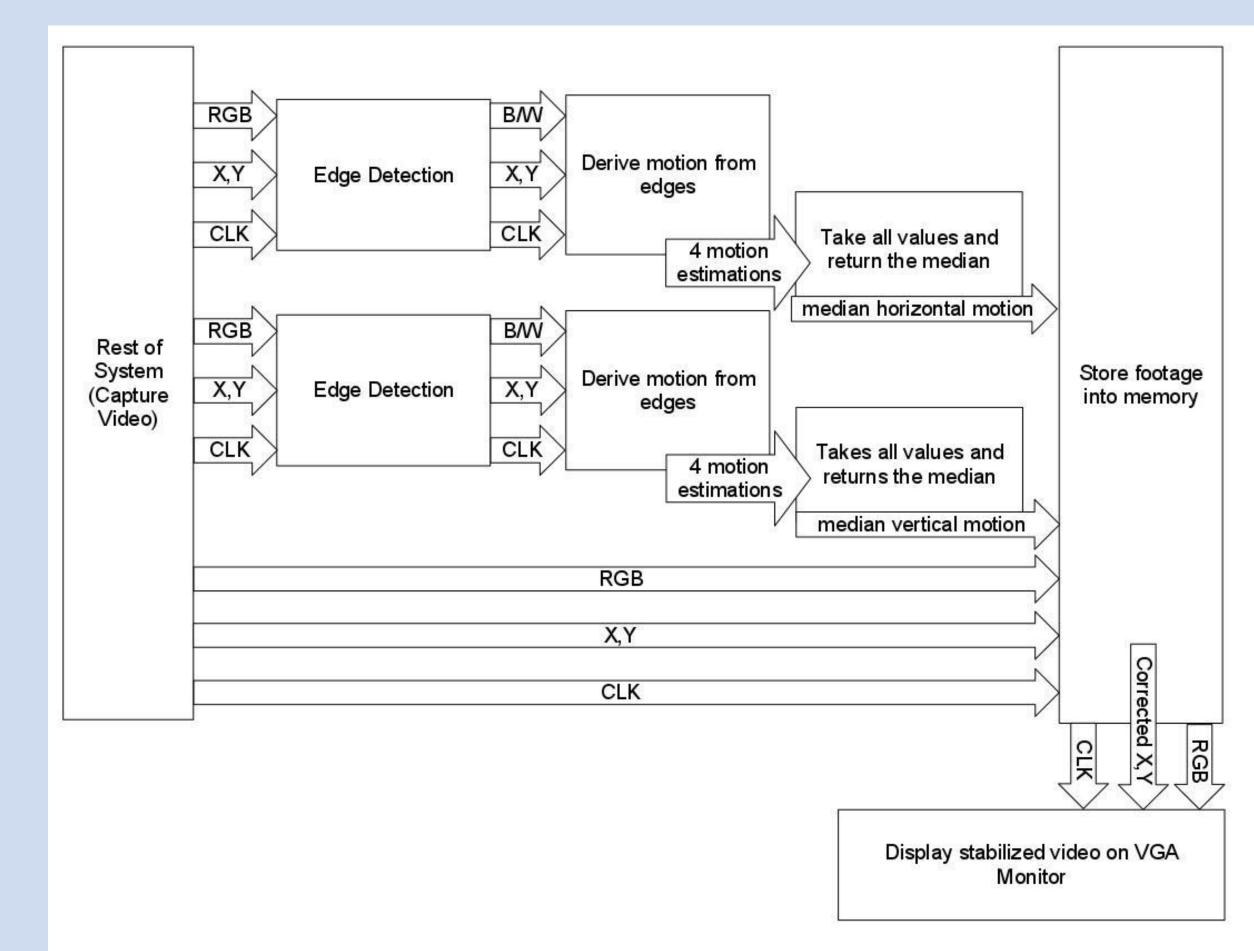


# MOTIVATION

Stabilizing shaky video is desirable in many applications but it does not come standard in many devices. This feature is available only in high value products such as the iPhone 4S, DSLR camera lens, etc. The objective is to prove that this concept can be easily implemented and be applied to other devices.

Users that find purpose for this application are ones who focus on using any type of camera for their work. This device could be used on police scanning machines, professional videographers, and surveillance cameras.

# SYSTEM ARCHITECTURE



# ACKNOWLEDGEMENTS

- TI
- Altera
- Professor Brehob
- Professor Emeritus Dr. Metzger

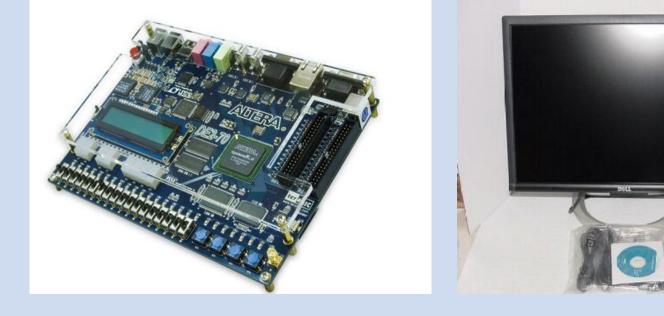
# **FIXATION SENSATION! Real-Time Video Stabilization**

Aminur Rahman, Sheila Raja, Nevetha Rajendran, Dagmara Wehr, Charlie Yan EECS 452 | Digital Signal Processing Laboratory | Fall 2011

# HARDWARE

- Bullet Telpix Bu 1004DN camera
- Altera DE2-70 FPGA board
- VGA monitor for display



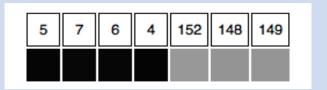


# **IMPLEMENTATION**

### Motion detection

Edge Detection: Find abrupt changes in consecutive pixel color values

Assign edges in frame based on thresholding these changes



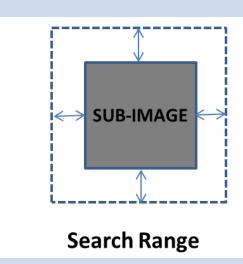
0 0 0 1 0 0

original pixel values

Frame comparison: Move current frame in se range and compare to previous frame Movement with the most matches of edges dee

the motion needed to correct





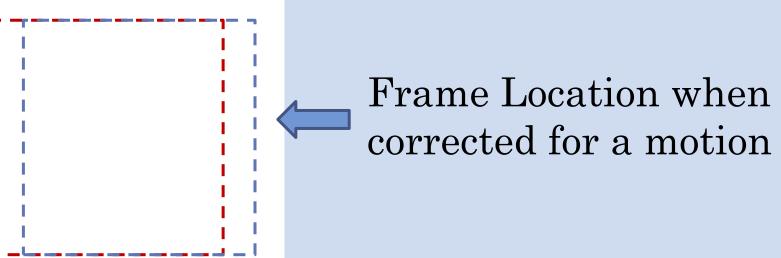
*Current video frame* 

### Motion correction

Previous video frame

Frame Shift: Shift frame to the location chosen by frame comparison

Original Frame\_ Location



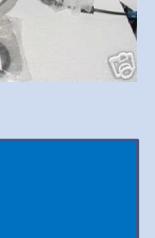
edges



# **DESIGN RATIONALE**

### Why Edge Detection?

Changing the threshold changes the number of edges used in motion detection. Increasing the number of edges leads to more accurate motion detection, but also increases the noise. Therefore, there is a tradeoff between the number of edges and amount of noise.



#### How Do We Compare Frames?

Perform an XOR operation using the 1s and 0s of the edge detected images and count the number of 1s. The 1s represent mismatches, and the comparison with the least 1s tells us the motion.

## FUTURE WORK

There are a number of ways we could improve our video stabilization system

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#### There are 3 main camera movements:

- Translational
- Rotational
- Scaling

We have successfully stabilized translational motion. With future work, we can stabilize rotational and scaling motion

There are 4 situations:

- Still scenes
- Object movement in frame
- Zooming
- Panning

We have successfully stabilized still scenes. With future work, we can allow object movement in frame, zooming and panning





