

# Complexity, P and NP

EECS 477

Lecture 21, 11/26/2002

## Last week

- Lower bound arguments
  - Information theoretic (12.2)
    - Decision trees (sorting)
  - Adversary arguments (12.3)
    - Maximum of an array
    - Graph connectivity
    - Median

## Linear reductions

- A is linearly reducible to B ( $A \leq B$ ) if the existence of a  $O(t(n))$  algorithm for B implies the existence of  $O(t(n))$  algorithm for A
- When both ways we get linear equivalence
  - Ex: SQR and MULT
    - $x^2 = x * x$
    - $x * y = ((x+y)^2 - (x+y)^2)/4$

Smoothness matters:  
see the book  
 $f(bN) = O(f(N))$ ,  
for all integer  $b \geq 2$

## Polynomial vs non-polynomial

- Linear reduction works for polynomial time algorithms
- Polynomial = efficient
- Distinguish efficient from the rest
  - Allow polynomial reduction
  - Polynomial number of polynomial-time operations takes polynomial time
  - Versus exponential time

## Decision problems

- Technically easier to handle decision problems
  - Answer is “yes” or “no”
- Example:
  - TSP
    - Find the tour of the minimum cost
  - TSPD: decision version
    - For  $K$ , is there a tour of cost  $\leq K$
    - We can **verify** given an example

## Hamiltonian cycles

- Hamiltonian path
  - Goes through every node once
  - Hamiltonian **cycle**
- HAM
  - Find Hamiltonian path if one exists
- HAMD
  - Is a given graph Hamiltonian?
    - Do not have to present the path

# Complexity classes

## ■ Two classes

### – P

- The class of decision problems that can be solved by a polynomial-time algorithm

### – NP

- The class of decision problems that **admit** a proof system  $F \subseteq X \times Q$ , poly-time algorithm A
  - 1:  $(\forall x \in X)(\exists q \in Q)$  s.t.  $(x, q) \in F$  and  $\#q \leq p(\#x)$
  - 2:  $(\forall (x, q))$  algorithm A can verify whether  $(x, q) \in F$
- Q - certificates (there are **q** for for “yes” instances **x** only), X - “yes” instances

## In other words,

- P – class of decision problems that can be **solved** by a polynomial-time algorithm

- NP – non-deterministic polynomial time

- Given a solution, it can be **checked** in polynomial time

- given a cycle/tour – check?
- Composite number: given a factor easy to check (but to find one?)

## Theorems, conjectures

- Theorem:  $P \subseteq NP$ 
  - If we can solve a problem then we can surely check it
- The central open question:  
Is  $P=NP$  or not?
- Conjecture:  $P \neq NP$ 
  - Look at the hardest problems in NP
    - As hard as any other problem in NP

Polynomial reduction

## Polynomial reductions

- Two problems A and B
- $A \leq^p B$  :
  - A is polynomially reducible to B
  - There is an algorithm for solving A in time that would be polynomial if we could solve arbitrary instances of B in unit time
  - If both ways then they are polynomially equivalent:  $A \equiv^p B$
  - Transitive: if  $A \leq^p B$  and  $B \leq^p C$  then  $A \leq^p C$

## Example

### ■ $\text{HAM} \equiv^p \text{HAMD}$

–  $\text{HAMD} \leq^p \text{HAM}$

- Trivial: if **HAM**algo finds a cycle then yes

–  $\text{HAM} \leq^p \text{HAMD}$

- First check if **HAMD**algo gives yes for the original graph
- Start considering edges **for removal** one by one
  - Apply **HAMD**algo to the remaining
  - If still Hamiltonian without an edge then remove it
  - Otherwise remove the edge and keep going
  - Stop when a cycle is left, return it

## Reduction function

### ■ Two decision problems $X \subseteq I$ and $Y \subseteq J$

### ■ $F: I \rightarrow J$

such that  $F(x) \in Y$  if and only if  $x \in X$

Theorem: If  $F$  is computable in polynomial time then  $X \leq^p Y$

```
• bool DecideX(x) {  
    y = F(x);  
    if (DecideY(y)) return true;  
    else return false;  
}
```

## Example

### ■ $\text{HAMD} \leq^p \text{TSPD}$

- Given a graph  $G=(N,A)$ , need to see if it is Hamiltonian
- Define  $F(G)$  be the TSPD instance with a complete graph  $(N, N \times N)$ 
  - Cost = 1 if the edge in  $A$  and 2 otherwise
  - TSPD bound being  $N$
  - If TSPD yes then that is a Hamiltonian cycle
  - If TSPD no then no Hamiltonian cycle

## NP-completeness

- Decision problem  $X$  is NP-complete
  1.  $X$  is in NP
  2.  $Y \leq^p X$  for **every** problem  $Y$  in NP
- $X$  is polynomially harder than any other NP problem
- If we know that  $X$  is NP-complete and  $X \leq^p Z$  then  $Z$  is NP-complete
- If we could only find one such  $X$

## SAT: satisfiability

- Given a boolean formula
  - Is it satisfiable?
    - is there an assignment of values to variables that will make it true?
    - e.g.  $(p \wedge q) \Rightarrow (p \vee q)$  is satisfiable via  $(p=q=\text{true})$
    - No efficient algorithm known
  - CNF: conjunctive normal form
    - e.g.  $(p+q+\neg r)(p+\neg q+\neg t)(\neg p+q+\neg r+t)p$
    - SAT-CNF satisfiability for boolean expressions in CNF form

## Cook's theorem

- For any NP problem  $Y$ ,  $Y \leq^p \text{SAT-CNF}$ 
  - Proof:
    - Any decision problem in NP has a decision algorithm  $A_y$  that checks a certificate
    - $A_y$  is given by a non-deterministic one-tape Turing machine program
    - Can construct polynomial size boolean CNF formula from that program
    - “Formula is satisfiable” = “Instance  $y$  is in  $Y$ ”
    - No more details here



## Some NP-complete problems

- SAT
- 3SAT: clauses have three variables
- 3DM: 3D matching
- HAMD: hamiltonian circuit
- PARTITION: set A and  $s:A \rightarrow \mathbb{Z}^+$ 
  - Partition A into two equally sized parts
- CLIQUE: clique of size J
- VERTEX COVER: of size K
- K-COL: graph colorability with K colors

## NP-hard

- X is NP-hard
  - if there is an NP-complete problem Y that can be polynomially reduced to X
    - $Y \leq^p X$
  - Does not have to be a decision problem
  - Decision problem can be NP-hard but not in NP, for instance exact K-colorability
    - Any K-coloring is a certificate for K-COL but not for K-COLE(exact)