

EECS483 D9: Midterm Exam Review

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Announcements

- Project 3 due on midnight Monday
- Extra office hour during 4-5pm next Monday

Problem A1: Which are Regular?

- (O) English words in Merriam-Webster Dictionary
 - Finite set
- (X) The set of all palindromes
 - Need $O(n)$ space to check
- (O) Strings that can be derived by " $E \rightarrow E + E \mid id$ "
 - $id \ ('+' \ id)^*$
- (O) Strings that can be derived by " $E \rightarrow E + E \mid (E) \mid id$ " in at most 100 derivation steps
 - Finite set
- (X) All regular expression strings
 - Need to match parentheses

Problem A2: Which are True?

- (O) Any ambiguous CFG is not LR(1)
- (X) Any unambiguous CFG is LR(1)
- (X) An unambiguous CFG can only have a unique derivation for each string in its language
 - Unique **leftmost/rightmost** derivation
- (O) If a CFG contains a shift/reduce conflict in LALR(1) parsing, then it would also contain a shift/reduce conflict in LR(1) parsing
 - LALR(1) doesn't introduce new s/r conflict
- (X) Language of an unambiguous CFG is regular

Problem B1

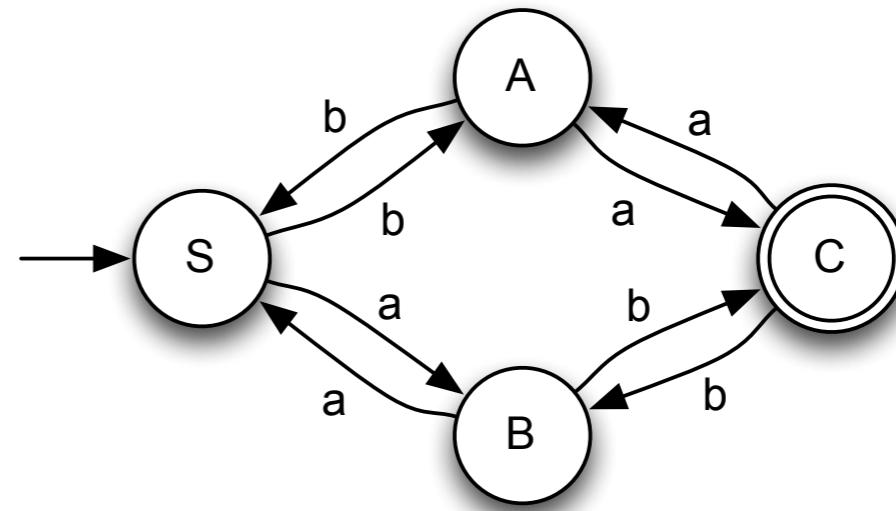
- $(ab|b)^+$ { printf("1"); }
- $[ab]?ab$ { printf("2"); }
- $(aa)^*a?b$ { printf("3"); }
- \cdot { printf("4"); }
- abab aaab abbab aab ab

Problem B2

- Counter example of `/*.* */`
 - Does not match newlines
 - Do longest match so won't terminate at the first appearance of ‘*/’

Problem B3

- $S \rightarrow aB \mid bA$
 $A \rightarrow aC \mid bS$
 $B \rightarrow bC \mid aS$
 $C \rightarrow aA \mid bB \mid \epsilon$



- A : strings with odd 'a's and even 'b's
B : strings with even 'a's and odd 'b's
C : strings with even 'a's and 'b's
S : strings with odd 'a's and 'b's
- $(aa|bb)^*((ab|ba)(aa|bb)^*(ab|ba)(aa|bb)^*)^* (ab|ba)(aa|bb)^*$

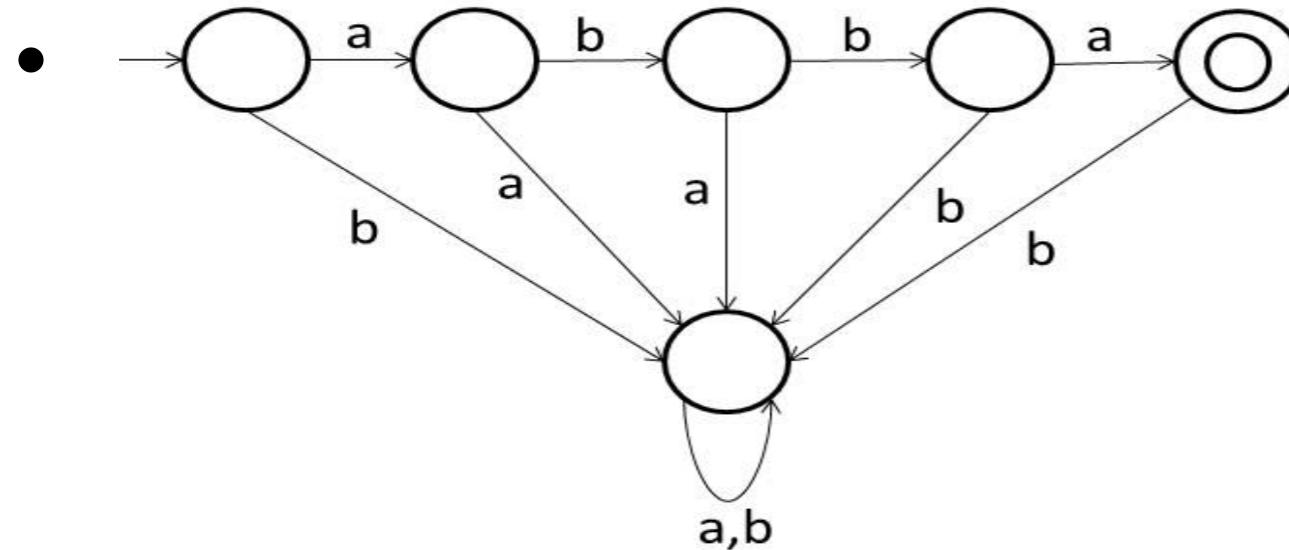
Problem B4

- L is regular, $S \subseteq L$, then is S regular?
– $L = [ab]^*$, S = balanced “a-b parentheses”

Problem B5

- $L = \{ x \mid x \in \Sigma^*, x \bmod 3 = 0 \text{ when interpreted as a number in binary} \}$
 - Given any binary string 101110
 - $(101110)_2 = 1 \times 2^5 + 0 \times 2^4 + 1 \times 2^3 + 1 \times 2^2 + 1 \times 2^1 + 1 \times 2^0$
 - next remainder := current remainder $\times 2 +$ next digit

Problem B6



- To make the complement of L
 - Add an erroneous state to recover all missing transitions
 - Swap the set of accepting states and non-accepting states

Problem B7

- All strings with at most two occurrences of the substring 00
- $(1|01)^* ((001(1|01)^*00 \mid 000 \mid 00) (1|10)^*)?$

Problem B8

• <pre>class A { void Set(int y) { x = y + 2; } void SetAndPrint(){ Set(2); Print(x); } }</pre>	class B extends A { void Set(int y){ x = y + 3; } }	class C extends A { int x; void SetAndPrint() { Set(4); Print(x); } }
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- Both A::Set() and B::Set() access the global x
- The Set() calls in A::SetAndPrint() and C::SetAndPrint() are dynamically dispatched
- C::SetAndPrint() prints out C::x, not the global x

Problem B8

```
void main() {  
    A a1;  
    A a2;  
    a1 = New(B);  
    a2 = New(C);  
    {  
        int x;  
        x = 5;  
        SetAndPrint(); set and print global x := 2  
        Print(x);      print local x = 5  
    }  
    a1.SetAndPrint();  
    a2.SetAndPrint();  
    Print(x);  
}
```

A::SetAndPrint() calls B::Set(2):
 set and printglobal x := 5
C::SetAndPrint() calls A::Set(4):
 set global x := 6 and print C::x = 0
print global x = 6

vtable for Problem B8

```
class A {  
    void Set(int y) {  
        x = y + 2;  
    }  
    void SetAndPrint(){  
        Set(2);  
        Print(x);  
    }  
}
```

```
class B extends A {  
    void Set(int y){  
        x = y + 3;  
    }  
}
```

```
class C extends A {  
    int x;  
  
    void SetAndPrint() {  
        Set(4);  
        Print(x);  
    }  
}
```

A::vtable

Index	Function Pointer
0	
1	

B::vtable

Index	Function Pointer
0	
1	

C::vtable

Index	Function Pointer
0	
1	

vtable for Problem B8

```
class A {  
    void Set(int y) {  
        x = y + 2;  
    }  
    void SetAndPrint(){  
        Set(2);  
        Print(x);  
    }  
}
```

```
class B extends A {  
    void Set(int y){  
        x = y + 3;  
    }  
}
```

```
class C extends A {  
    int x;  
  
    void SetAndPrint() {  
        Set(4);  
        Print(x);  
    }  
}
```

A::vtable

Index	Function Pointer
0	● →
1	

B::vtable

Index	Function Pointer
0	
1	

C::vtable

Index	Function Pointer
0	
1	

vtable for Problem B8

```
class A {  
    void Set(int y) {  
        x = y + 2;  
    }  
    void SetAndPrint(){  
        Set(2);  
        Print(x);  
    }  
}  
  
class B extends A {  
    void Set(int y){  
        x = y + 3;  
    }  
}  
  
class C extends A {  
    int x;  
    void SetAndPrint() {  
        Set(4);  
        Print(x);  
    }  
}
```

A::vtable

Index	Function Pointer
0	● →
1	● →

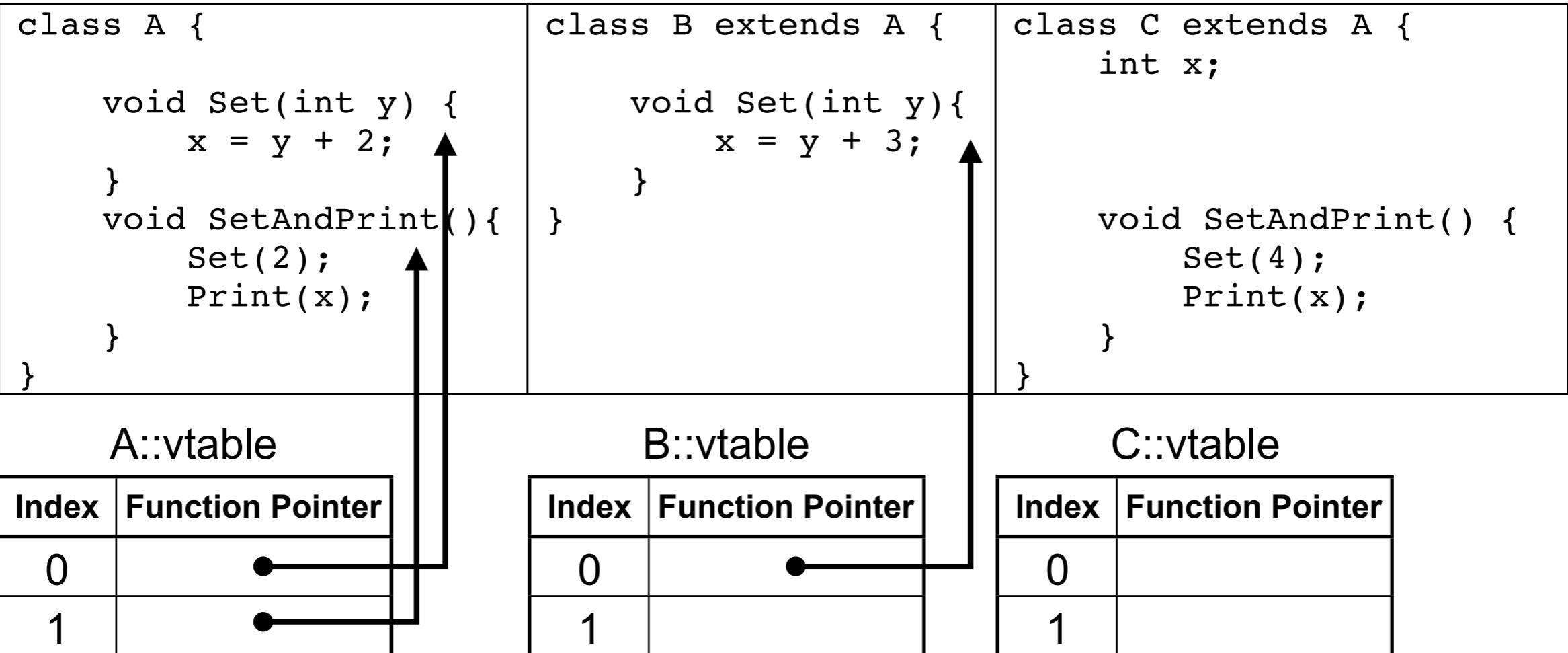
B::vtable

Index	Function Pointer
0	
1	

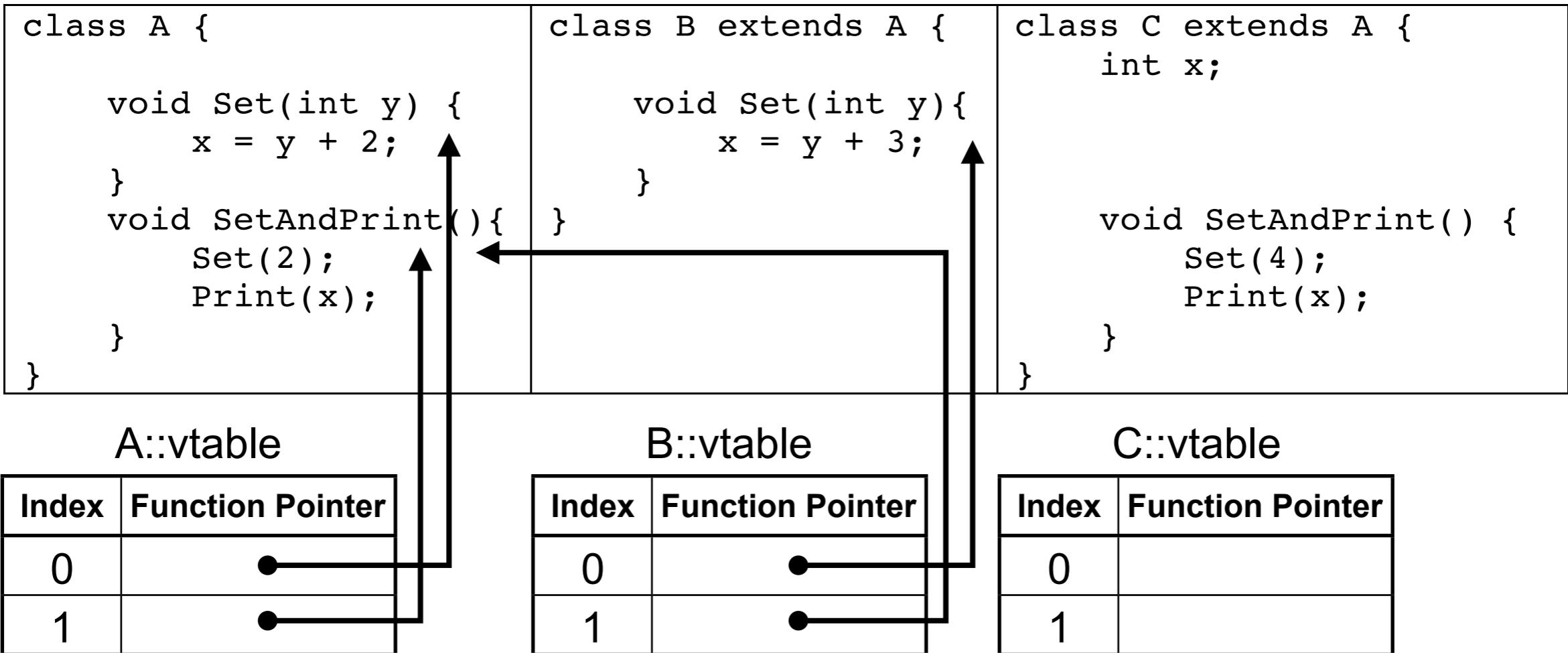
C::vtable

Index	Function Pointer
0	
1	

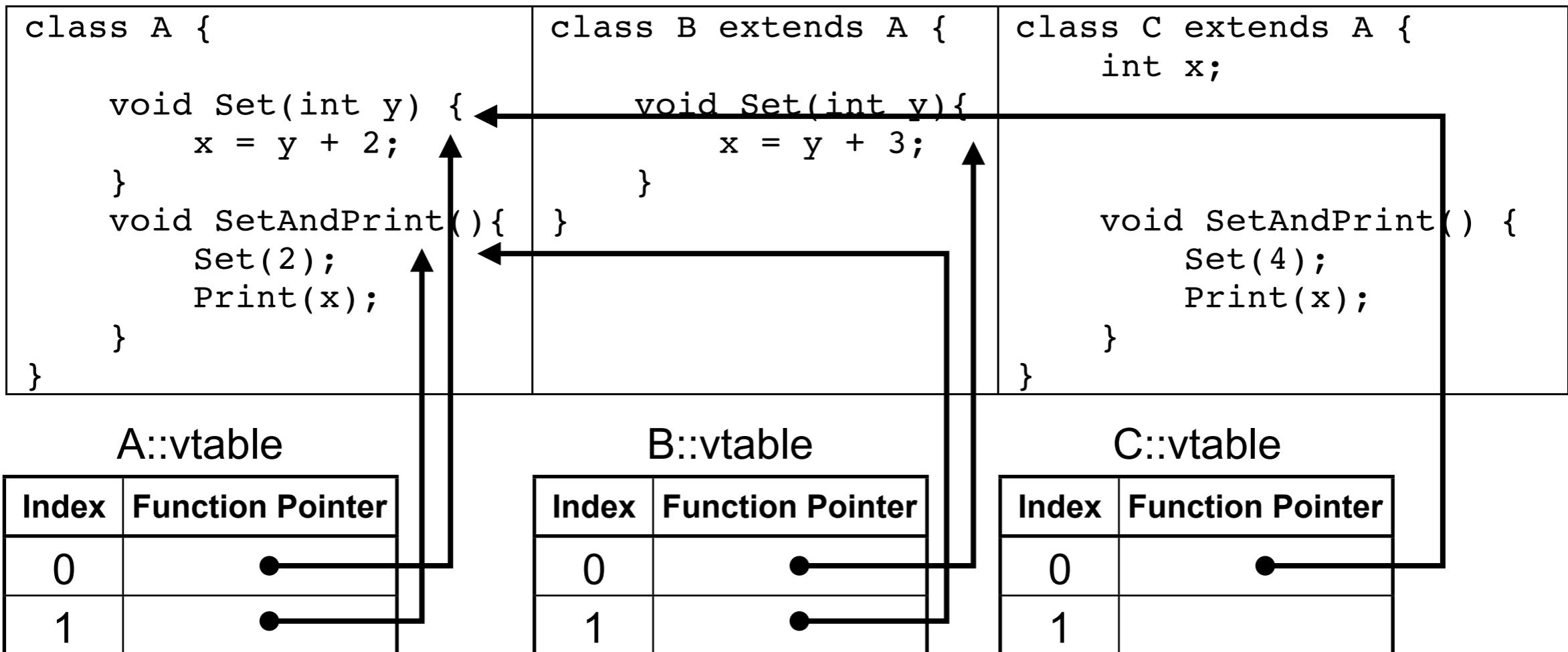
vtable for Problem B8



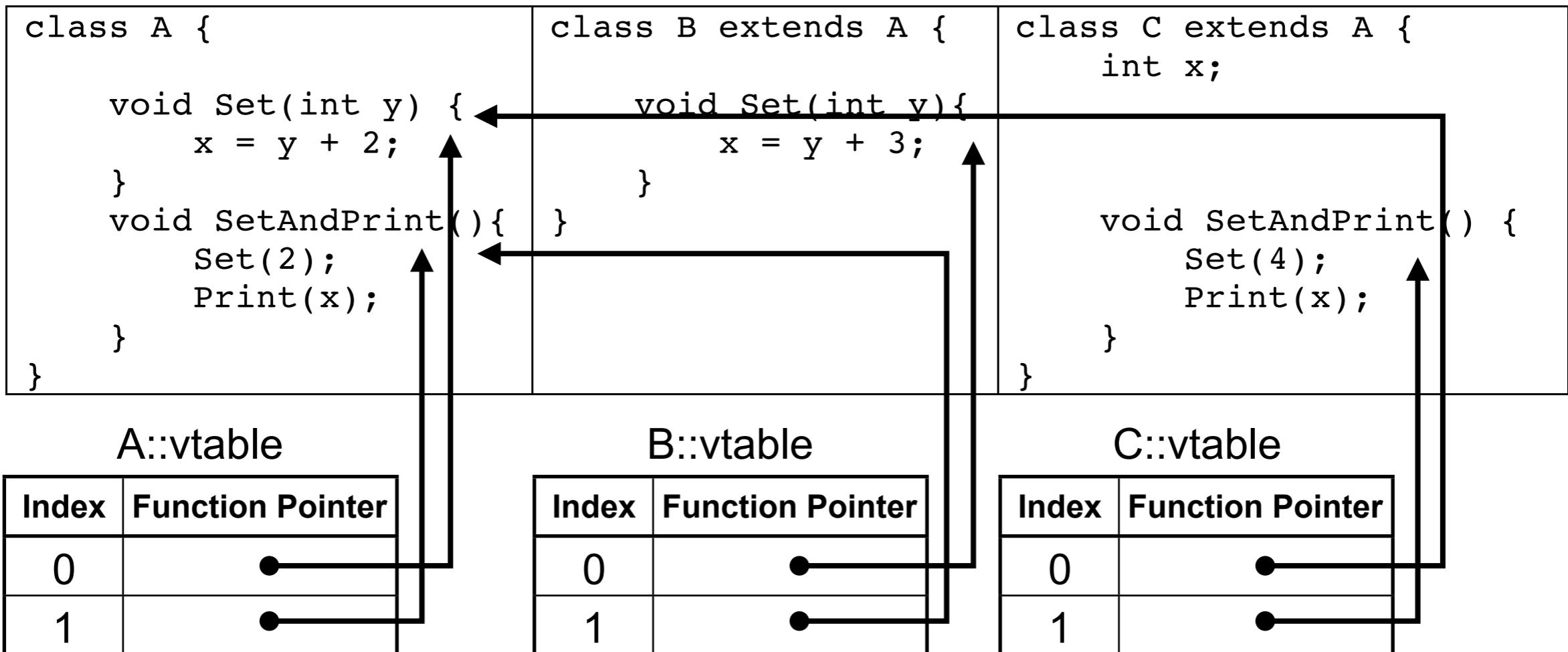
vtable for Problem B8



vtable for Problem B8



vtable for Problem B8



vtable for Problem B8

```
void main() {  
    A a1;  
    A a2;  
    a1 = New(B);  
    a2 = New(C);  
    {  
        int x;  
        x = 5;  
        SetAndPrint();  
        Print(x);  
    }  
    a1.SetAndPrint();  
    a2.SetAndPrint();  
    Print(x);  
}
```

A::vtable

Index	Function Pointer
0	
1	

B::vtable

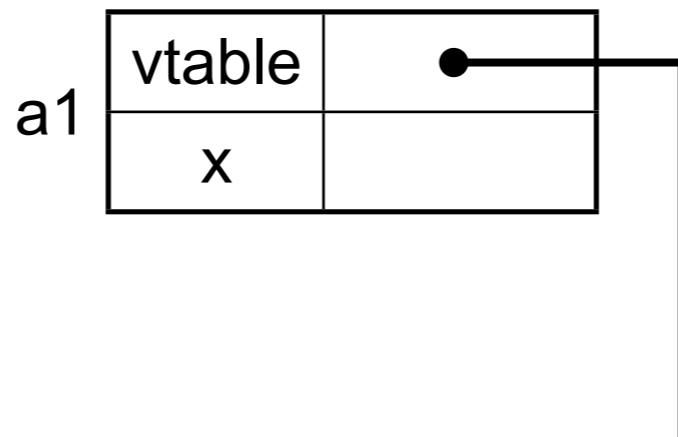
Index	Function Pointer
0	
1	

C::vtable

Index	Function Pointer
0	
1	

vtable for Problem B8

```
void main() {
    A a1;
    A a2;
    a1 = New(B);
    a2 = New(C);
{
    int x;
    x = 5;
    SetAndPrint();
    Print(x);
}
a1.SetAndPrint();
a2.SetAndPrint();
Print(x);
}
```



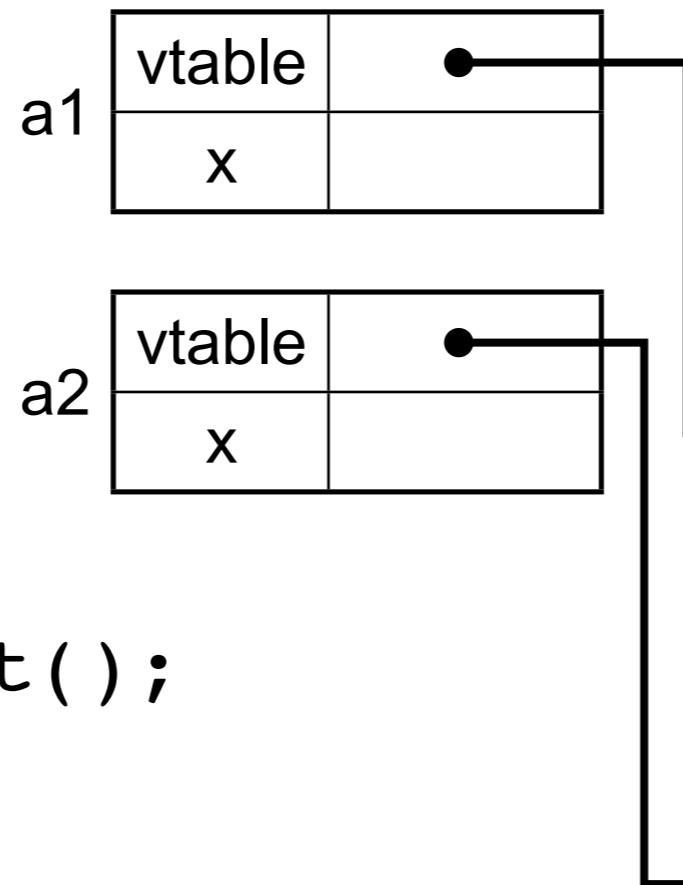
A::vtable	
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C::vtable	
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vtable for Problem B8

```
void main() {
    A a1;
    A a2;
    a1 = New(B);
    a2 = New(C);
{
    int x;
    x = 5;
    SetAndPrint();
    Print(x);
}
a1.SetAndPrint();
a2.SetAndPrint();
Print(x);
}
```



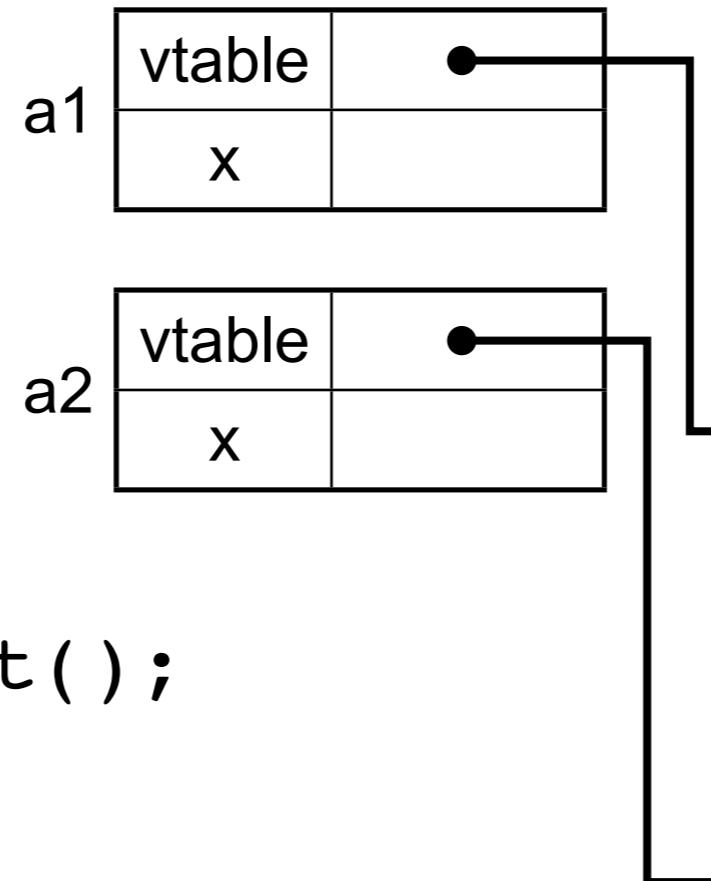
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B::vtable	
Index	Function Pointer
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1	

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vtable for Problem B8

```
void main() {
    A a1;
    A a2;
    a1 = New(B);
    a2 = New(C);
{
    int x;
    x = 5;
    SetAndPrint();
    Print(x);
}
a1.SetAndPrint(); load $t0, a1.vtable;
a2.SetAndPrint(); load $r1, $t0[1];
Print(x);          jr $r1;
```



A::vtable	
Index	Function Pointer
0	
1	

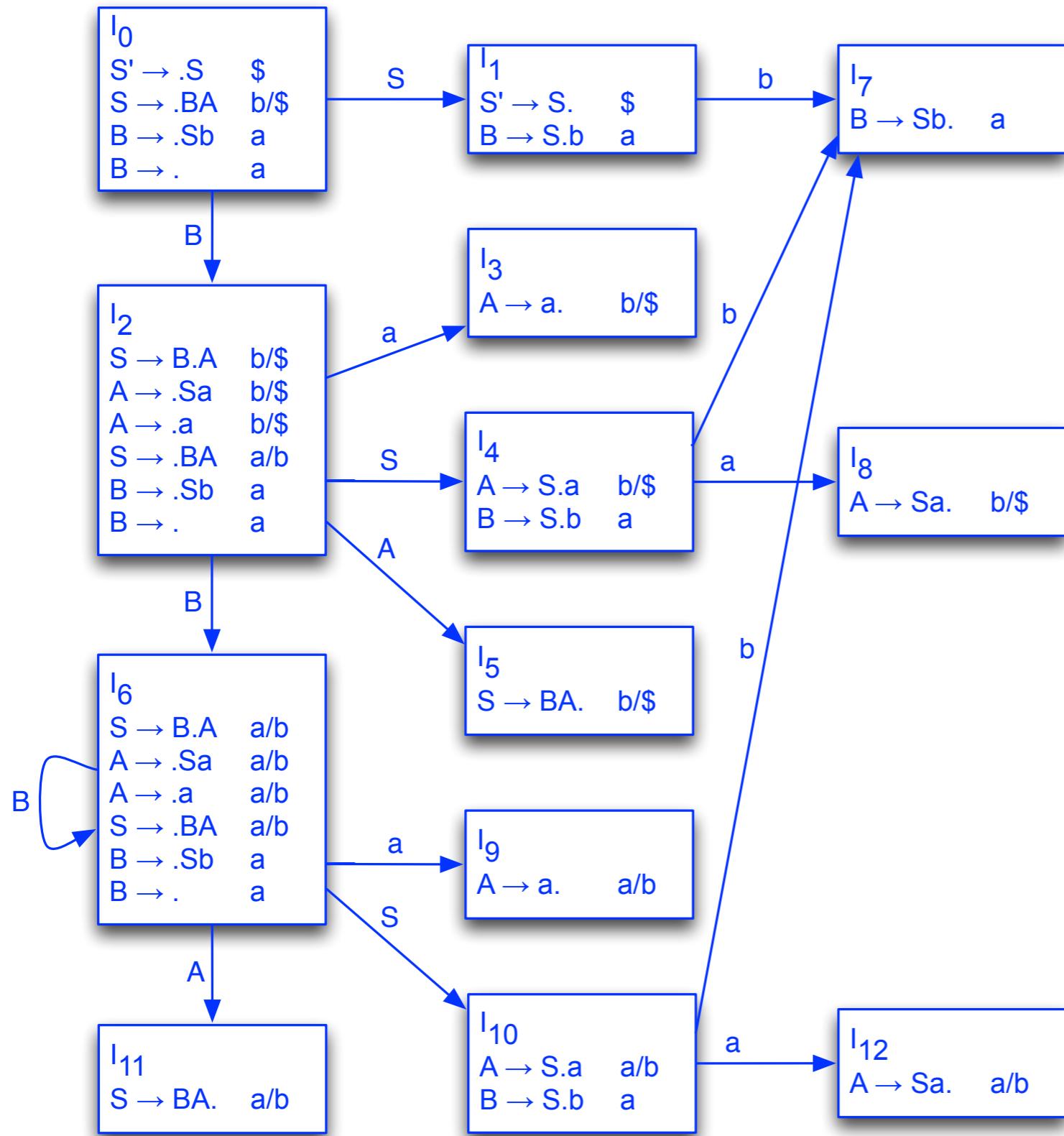
B::vtable	
Index	Function Pointer
0	
1	

C::vtable	
Index	Function Pointer
0	
1	

Problem C1

- $S \rightarrow BA$
 $A \rightarrow Sa \mid a$
 $B \rightarrow Sb \mid \epsilon$
- Remove the ϵ -production:
 $S \rightarrow BA \mid A$
 $A \rightarrow Sa \mid a$
 $B \rightarrow Sb$
- $S \rightarrow BA \mid A$
 $A \rightarrow BAaA' \mid aA'$
 $A' \rightarrow aA' \mid \epsilon$
 $B \rightarrow aA'bB'$
 $B' \rightarrow AbB' \mid AaA'bB' \mid \epsilon$

Problem C1



Problem C2

- $R \rightarrow R \mid R$ (alternation operation)
 $R \rightarrow RR$ (concatenation operation)
 $R \rightarrow R^*$ (repetition)
 $R \rightarrow (' R ')$
 $R \rightarrow a \mid b$
- $R \rightarrow RR \rightarrow \underline{RRR} \rightarrow^* aaa$
 $R \rightarrow RR \rightarrow aR \rightarrow a\underline{RR} \rightarrow^* aaa$

Problem C3

- $S \rightarrow AaAb \mid BbBa$
 $A \rightarrow \epsilon$
 $B \rightarrow \epsilon$
- $L(S \rightarrow AaAb) = \{a\}, L(S \rightarrow BbBa) = \{b\} \Rightarrow LL(1)$
- $\text{FOLLOW}(A) = \text{FOLLOW}(B) = \{a,b\}$
 - Don't know whether to reduce ϵ to A or B

Thanks & all the best!
