



Modeling

Lecture
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Modeling - Numeric Representation of
a Physical Object or Process

- Geometric Modeling
 - 3-D Coordinate Description of Objects
- Physics Modeling
 - Illumination (Light / Color)
 - Reflection (EM Scattering)
 - Interacting Forces (Jell-O)
- Motion Modeling
 - Animation
 - Camera Location

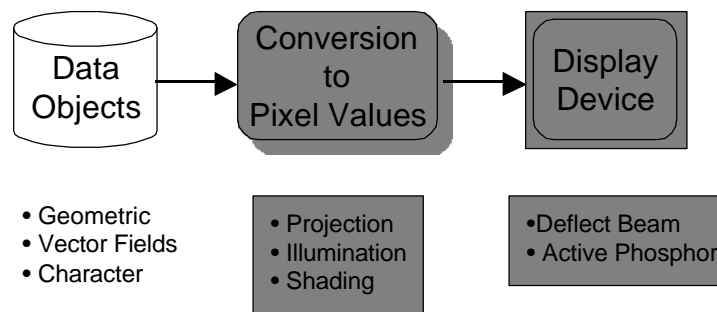
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Modeling

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- Graphics Pipeline



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Modeling

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- Methods of Geometric Modeling
 - Boundary Representation (B-rep)
 - Interior / Exterior Interface
 - Spatial Representation
 - Interior Volume Cubes
- Space vs. Time Trade-off
- Development Tools
 - CAD Packages
 - User Applications
- Standards / Formats ????
 - PHIGS
 - Storage
 - Processing

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Boundary Representation

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- Surface Modeling
 - Quadratic Surfaces
 - Polygons / Facets
 - Splines
- Solid Modeling
 - Boolean Operators on Geometric Primitives

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Quadratic Surfaces

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- Exact Representation of Surface
- Limited Number of Shapes

$$f(x, y, z) = Ax^2 + By^2 + Cz^2 + 2Dxy + 2Eyz + 2Fxz + 2Gx + 2Hy + 2Jz + K = 0$$

Sphere : $A = B = C = 1$
 $K = -r^2$
 All others = 0

Plane : A thru F = 0

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Quadratic Surfaces

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- Matrix Formulation

$$[Q] = \begin{bmatrix} A & D & F & G \\ D & B & E & H \\ F & E & C & J \\ G & H & J & K \end{bmatrix} \quad [P] = \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

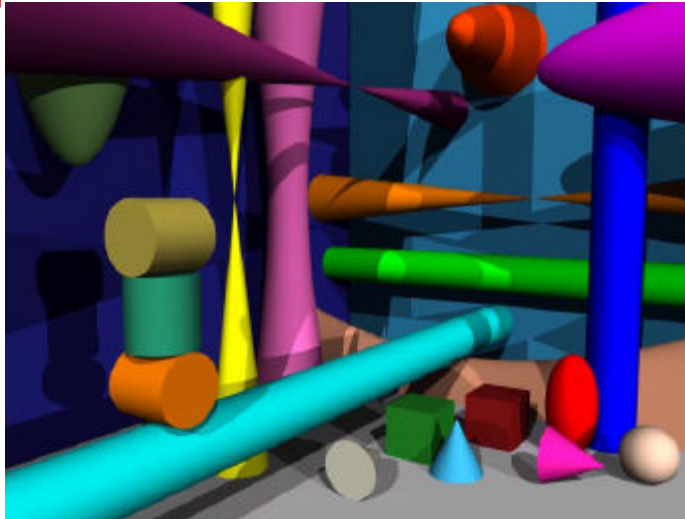
$$f(x, y, z) = [P]^T [Q] [P]$$

- Operate on [Q] with 4x4 Transformation Matrices
- Compute Surface Normal $[N] = [\partial f / \partial x \quad \partial f / \partial y \quad \partial f / \partial z]$
- Test a Point wrt the Surface

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Quadratic Surfaces

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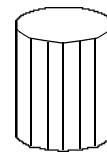


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Polygons

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- Good Representation for Planar Surfaces
- Approximation of a Curved Surface with Piecewise Linear Segments
- Smaller/More Facets Give Closer Approximation
- Special Hardware Provides Rapid Rendering
- Tessellation – Convert Forms into Polygons



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Polygon Data

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- Polygon Data Files

- Explicit Polygon Vertices
 - Difficult Interaction
 - Redundant

$$P_1 = \{(V_{x1}, V_{y1}, V_{z1}), (V_{x2}, V_{y2}, V_{z2}), \dots, (V_{xn}, V_{yn}, V_{zn})\}$$

$$P_2 = \{(V_{xn+1}, V_{yn+1}, V_{zn+1}), \dots, (V_{xn+m}, V_{yn+m}, V_{zn+m})\}$$

- Vertex Table
 - Number of Vertices
 - Polygon Vert's CCW

$$V = \{(x_1, y_1, z_1), (x_2, y_2, z_2), \dots, (x_n, y_n, z_n)\}$$

$$P_1 = \{1, 3, 6\} \quad P_2 = \{2, 4, 5\}$$

- Edge Table
 - Shared Edges

$$V = \{V_1, V_2, \dots, V_n\}$$

$$E_1 = \{V_1, V_2\} \quad E_2 = \{V_2, V_3\} \quad E_3 = \{V_3, V_1\}$$

$$P_1 = \{E_1, E_2, E_3\} \quad P_2 = \{E_3, E_4, E_5, E_6\}$$

- Ancillary Data
 - Normal Vectors
 - Material Type
 - Shading Coefficients
 - Transparency

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Polygon Error Checking

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- Every Vertex is an End Point for at Least Two Edges
- Every Edge is a Part of at Least One Polygon
- Every Polygon is Closed
- Every Polygon Has at Least One Shared Edge

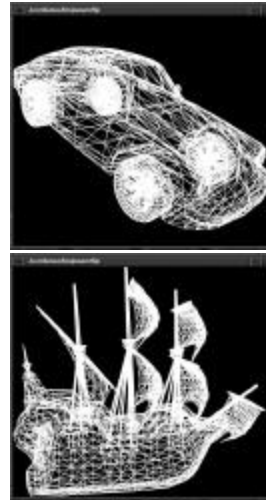
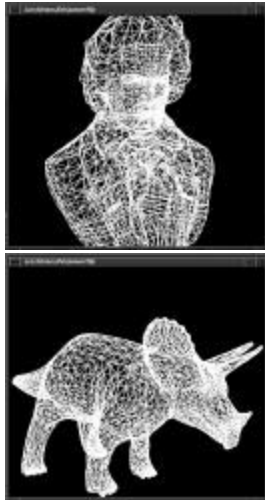
Waterproof Models

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Polygon WireFrames

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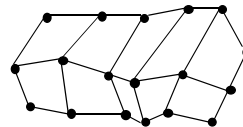
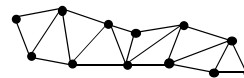
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Polygon Mesh

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- Triangular Mesh
 - Guaranteed Coplanar Points
 - Compute Normal with Cross Product
- Quadrilateral Mesh
 - Points May Not Be Planar
 - Approximate Normal
 - OR
 - Convert to Triangular
- Fan Mesh
 - Common Center point
 - Guaranteed Coplanar Points



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Polygon Normals

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Polygon Vertices in CCW Order
when viewed from Outside

$$\vec{V}_1 = \langle (P_{x2} - P_{x1}), (P_{y2} - P_{y1}), (P_{z2} - P_{z1}) \rangle$$

$$\vec{V}_2 = \langle (P_{x3} - P_{x1}), (P_{y3} - P_{y1}), (P_{z3} - P_{z1}) \rangle$$

$$\vec{N} = \vec{V}_1 \times \vec{V}_2$$

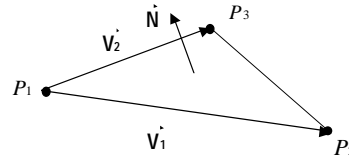
Plane Eqn :

$$Ax + By + Cz + D = 0$$

$$[N] = [A \ B \ C] \quad [P] = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$D = -([N] \cdot [P_n])$$

P is any point
on the plane



$$Ax + By + Cz + D > 0$$

[P] is above the plane (Outside the surface)

$$Ax + By + Cz + D < 0$$

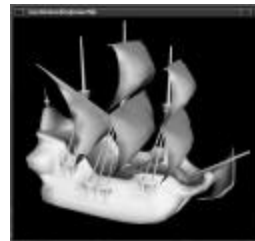
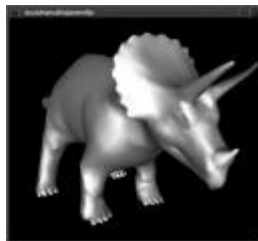
[P] is below the plane (Inside the surface)

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Polygon Normals

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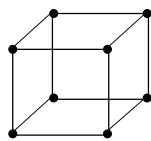


Solid Modeling

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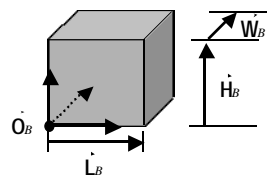
- CSG - Constructive Solid Geometry
- Widely Used in CAD/CAM Packages
 - Object modeling for
 - Casting
 - Machining
 - Extruding

B-Rep of a Box



8 Vertices ==> 24 floats
12 Edges
6 Polygon faces

Solid Model of a Box



Vectors for the Origin, Length, Width, and Height
4 Vectors ==> 12 floats

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Solid Modeling

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- Set of Geometric Primitives
 - Blocks
 - Pyramids
 - Cylinders
 - Spheres
 - etc.
- Combine Primitives with Boolean Operators
 - Union (A OR B)
 - Intersection (A AND B)
 - Difference (A Minus B)



$$A \cup B$$

$$A \cap B$$

$$A - B$$

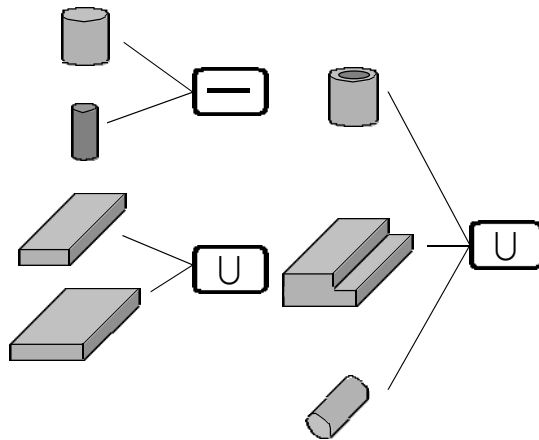
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E
E
C
S

4
8
7

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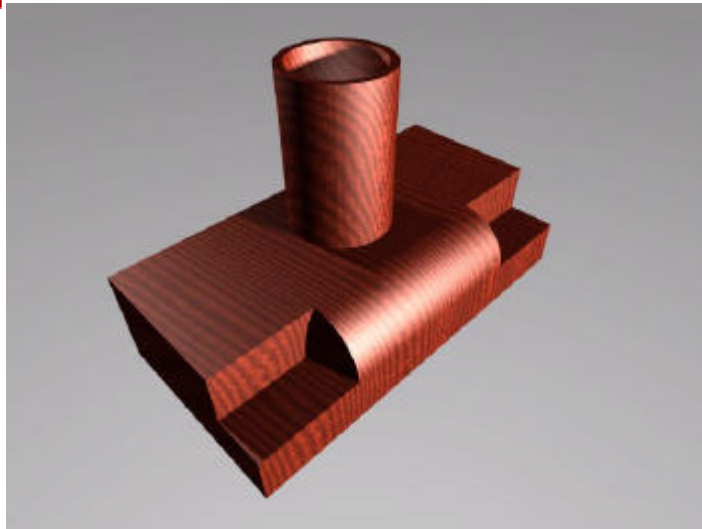
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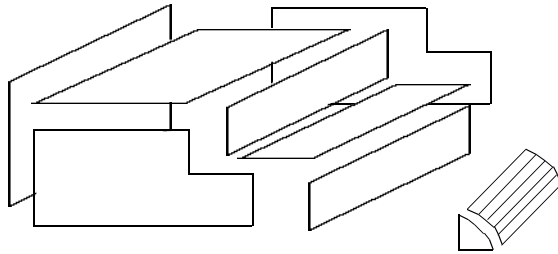


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Facet Modeling

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Solid Modeling

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Drawbacks

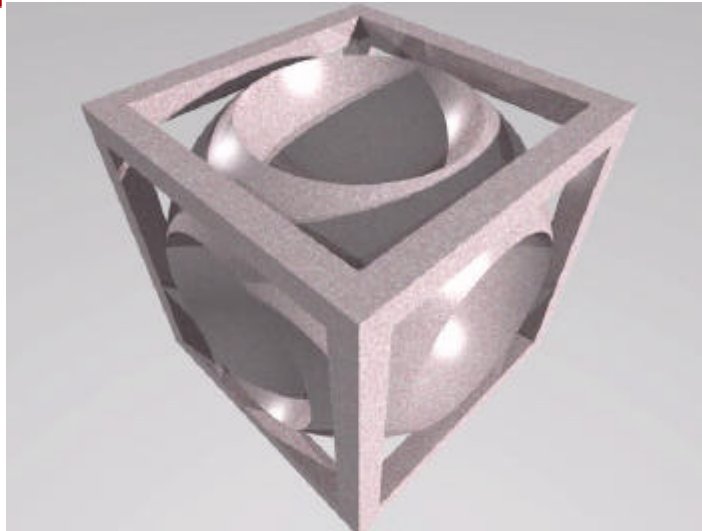
- Difficult to model arbitrary surface
- Increased computation when rendering

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Solid Modeling

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