



Texture Mapping

Lecture
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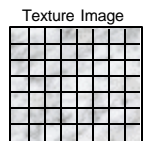
- Increase Object Detail
 - Paint
 - Decal
 - Material
 - Wood Grain
 - Marble
 - Non-Plastic
 - Geometry
 - Surface Normal
 - Surrounding Environment
 - Reflection
 - Transparency (Clouds)
- Increased Computation Time

1

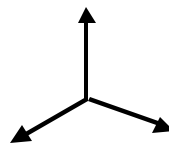


Texture Mapping

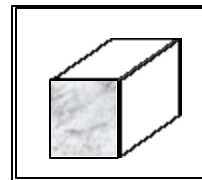
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• Texture Space
(s, t)



• Object Space
(u, v)

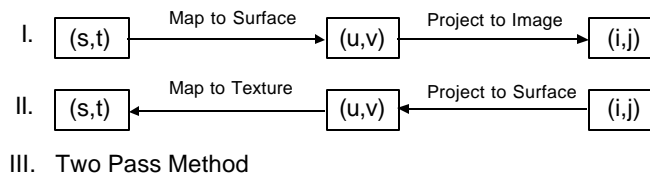


• Rendered Image Space
(i, j)

• Texels

• Parametric Surface

• Pixels

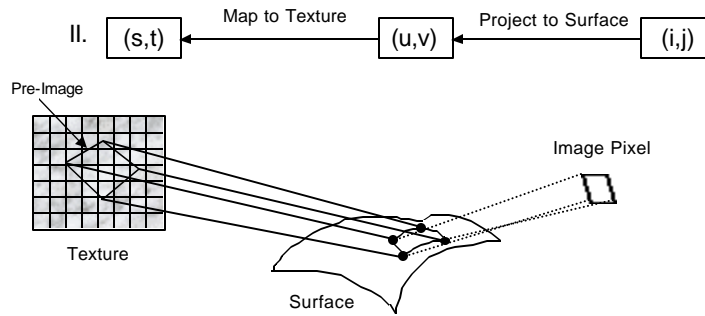


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Texture Mapping

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- Project 4 Pixel Corners Onto Parametric Surface(u,v)
- Transform Parametric Surface Values to Texel Space (s,t)
- Compute Weighted Sum of Texels in Bounding Quadrilateral
- Set Image Pixel Value

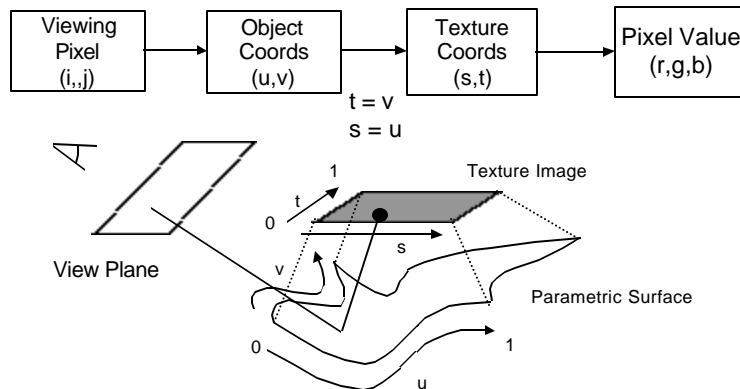
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- Shrinkwrapping Image Onto a Parametric Surface



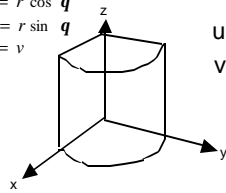
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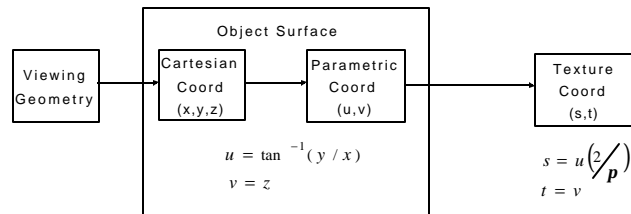
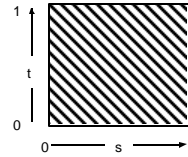
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$$\begin{aligned} x &= r \cos q \\ y &= r \sin q \\ z &= v \end{aligned}$$



$$\begin{aligned} u &= \theta & 0 \leq \theta \leq p/2 \\ v &= z & 0 \leq z \leq 1 \end{aligned}$$



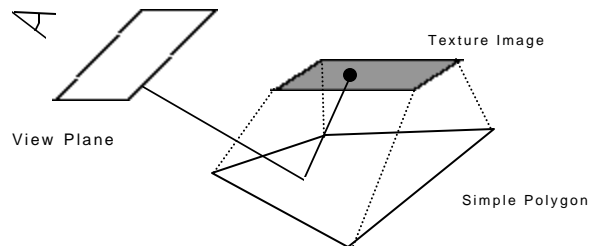
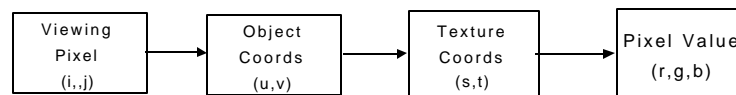
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- "Vacuum-Form" Image Onto a Polygonal Surface



- Assign Texture Coordinates to Polygon Vertices

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Texture Mapping

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- Polygon Mesh Texture Mapping ?
- Two-Part Mapping
 - Map Texture onto an intermediate surface
 - Generally non-planar
 - Possesses a simple parametric definition
 - Map intermediate surface onto object
 - Correspondence between object point and texture point is a 3-D to 3-D transform
- Handles "global" mapping of polygon meshes
- Texture may be distorted by double mapping

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Two Pass Texture Mapping

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- Map from 2-D Texture Space to a *simple* 3-D intermediate surface
 - Cylinder
 - Sphere
 - Box
 - Plane

$$T(s, t) \rightarrow T'(x_i, y_i, z_i) \quad \text{"S" mapping}$$

- Determine mapping from 3-D intermediate surface to 3-D object surface

$$T'(x_i, y_i, z_i) \rightarrow O(x, y, z) \quad \text{"O" mapping}$$

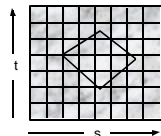
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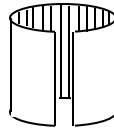
Two Pass Texture Mapping

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• "S" mapping



Texture
(s,t)



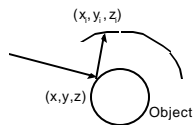
Surface
(θ, h)

$$s = \frac{r}{c} (\mathbf{q} - \mathbf{q}_0)$$

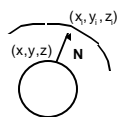
$$t = \frac{1}{d} (h - h_0)$$

c, d are scaling factors
 θ_0, h_0 position the texture on the cylinder
 r is the radius of the cylinder

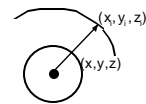
• "O" mapping



Reflected Ray



Object Normal



Object Centroid

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Two Pass Texture Mapping

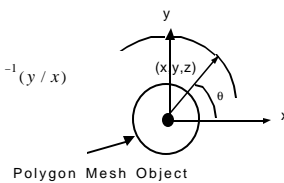
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1. Map the four pixel corners to the surface of the object
(x,y,z)

2. Apply the "O" mapping
(θ, h)

$$\theta = \tan^{-1}(y/x)$$

$$h = z$$



3. Apply "S" mapping to find texture point
(s,t)

$$s = \frac{r}{c} (\mathbf{q} - \mathbf{q}_0)$$

$$t = \frac{1}{d} (h - h_0)$$

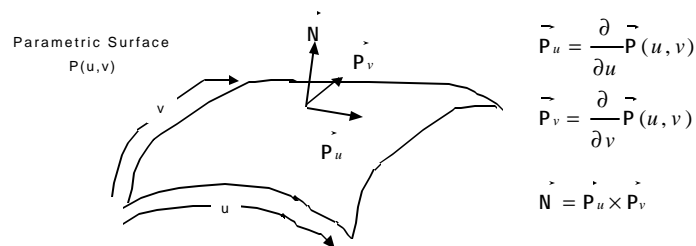
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Bump Mapping

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- Bump Mapping
 - Texture map image shadows won't change if scene lighting changes
 - Modify surface itself instead of surface color
 - Simulate wrinkled/rough surfaces [Blinn '78]

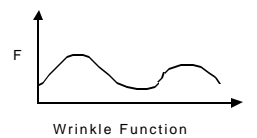
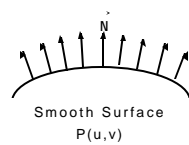


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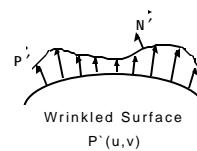
Bump Mapping

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$$\vec{P}' = \vec{P} + F(u,v)\hat{n}$$

where F is the wrinkle function



$$\vec{N}' = \vec{P}'_u \times \vec{P}'_v$$

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Bump Mapping

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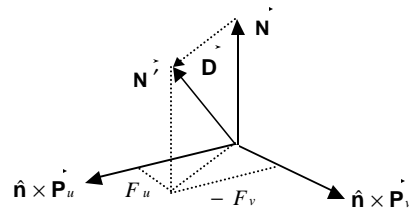
$$\vec{N}' = \vec{P}'_u \times \vec{P}'_v$$

$$\vec{P}'_u = \frac{\partial}{\partial u}(\vec{P} + F\hat{n}) = \vec{P}_u + F_u\hat{n} + F\hat{n}_u$$

Let F be small, so that the last term can be neglected

$$\vec{P}'_v = \frac{\partial}{\partial v}(\vec{P} + F\hat{n}) = \vec{P}_v + F_v\hat{n} + F\hat{n}_v$$

$$\vec{N}' = \vec{N} + \vec{D} = \vec{N} + \{F_u(\hat{n} \times \vec{P}_v) - F_v(\hat{n} \times \vec{P}_u)\}$$

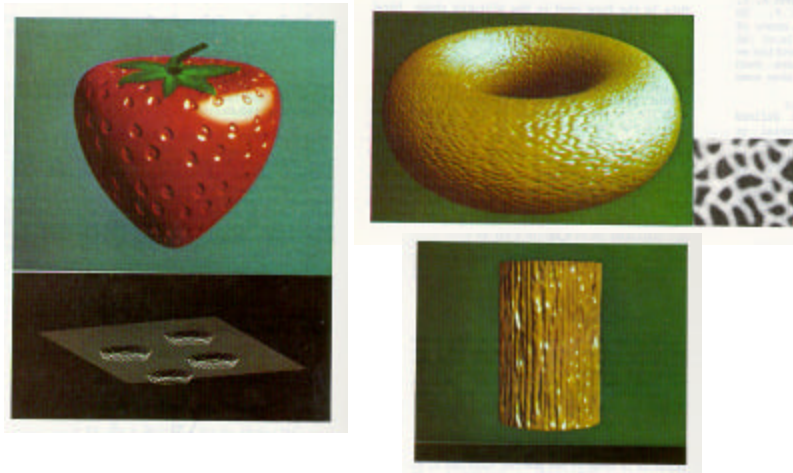


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Bump Mapping

Lecture
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OpenGL Implementation

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- Texture Mapping in OpenGL
 - Create a Texture Object
 - Specify Texture for the Object
 - Define How the Texture is to be Applied
 - GL_DECAL, GL_REPLACE
 - Enable Texture Mapping
 - Draw the Scene
 - Supply Texture Coordinates
 - Supply Geometric Coordinates
- **Size of Textures Must be a Power of 2**
 - **Minimum Size : 64x64**

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Advanced Texturing

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Mip Mapping
Environment Mapping
Procedural Textures

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MIP Maps

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MIP Latin

“multum in parvo”

“Many things in one place”

- Pre-filtered Offline
- Multi Levels of detail
- mip maps accessed through u,v,d
- `gluBuild2DMipmaps` `gluBuild1DMipMaps`

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Environment Maps

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- Simulates specular reflected scene information
- Provides a virtual 1 ray ray-trace
- Only provide far field reflection correctly
- Can be mapped to a cube for easy access

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E
E
C
S

4
8
7

Environment Maps

Lecture
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19

E
E
C
S

4
8
7

Environment Maps

Lecture
10



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Procedural Textures

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- Textures Based on functions not images
- Simulate the natural world through simplified Physics
- Noise Generators and Fractals
- 3-D Textures
- Not only colors but, materials, motion

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Procedural Textures

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Advantages

- Very compact when compared to images.
- No fixed resolution
- No fixed area
- Can be parameterized for general classes

Disadvantages

- Difficult to code and debug
- Not always predicable
- Can be slow
- Aliasing can be a problem

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Procedural Textures

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Wood Example

Simulate wood in 3-D

Growth rings

Color

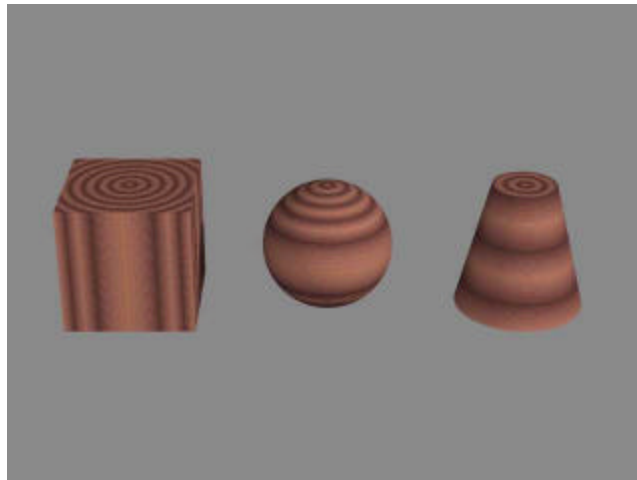
Position

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Procedural Textures

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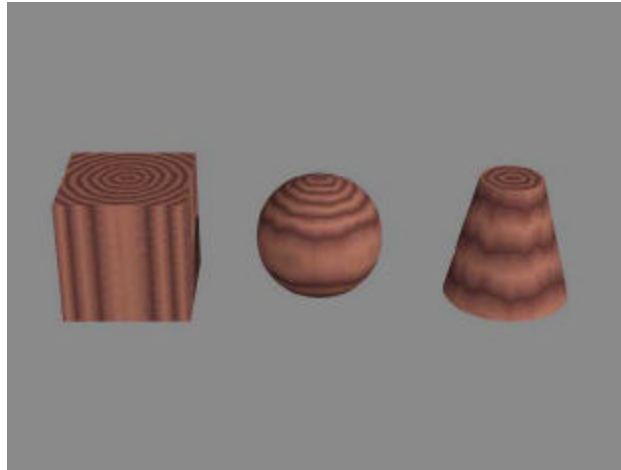


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Procedural Textures

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Procedural Textures

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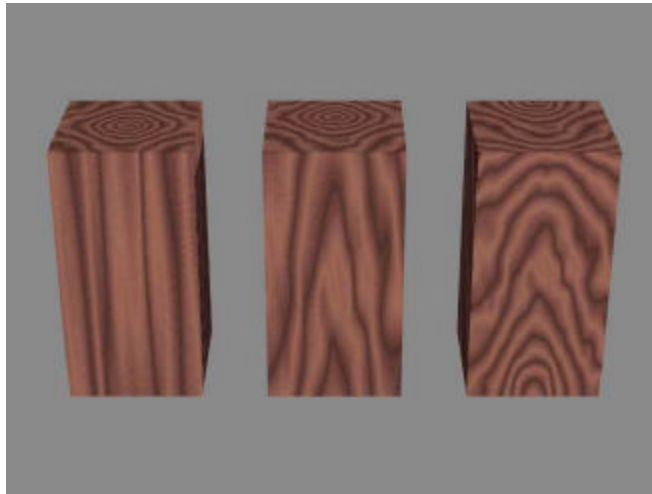


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Procedural Textures

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Procedural Textures

Lecture
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Procedural Textures

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