Appendix A

Probability, Random Variables and Random Processes

In this appendix basic concepts from probability, random processes and signal theory are reviewed.

1. Probability and Random Variables

Probability Space (Ω, \mathcal{F}, P) Ω is the sample space or set of all possible outcomes. \mathcal{F} is a collection of events which are subsets of Ω (algebra, field)

$$A \in \mathcal{F}, B \in \mathcal{F} \Rightarrow A \cup B \in \mathcal{F};$$

$$\Omega \in \mathcal{F},$$
$$A \in \mathcal{F} \Rightarrow \bar{A} \in \mathcal{F}$$

P is a function from $\mathcal{F} \rightarrow [0,1]$ which satisfies

- i) $0 \le P(A) \le 1$, $A \in \mathcal{F}$
- ii) $P(\Omega) = 1$
- iii) If $A \cap B = \emptyset$ then $P(A \cup B) = P(A) + P(B)$ $A, B \in \mathcal{F}$

A random variable X(w) is a function from Ω to R

 $X:\Omega\to R$

that satisfies

$$\{w \in \Omega : X(w) \le x\} \in \mathcal{F} \ \forall x \in R$$

The distribution function $F_X(x)$ of a random variable is defined as

$$F_X(x) = P\{X(w) \le x\} = P\{w \in \Omega : X(w) \le x\}$$

Properties of distribution functions

- (i) $P\{a < X(w) \le b\} = F_X(b) F_X(a)$
- (ii) $F_X(x)$ is continuous at x iff $P\{X(w) = x\} = 0$
- (iii) $\lim_{y \downarrow x} F_X(y) = F_X(x)$ right continuous

(iv) $\lim_{x \to \infty} F_X(x) = 1$, $\lim_{x \to -\infty} F_X(x) = 0$

If $F_X(x)$ is continuous for all x then there exists a function $f_X(x)$ such that

$$F_X(x) = \int_{-\infty}^x f_X(u) du$$

This function is called the density function. If a random variable has a density function we shall say the random variable is continuous.

Properties of density functions

(i)
$$P{X(w) \in B} = \int_B f_X(u) du \ B \subset R$$

(ii)
$$f_X(x) = F'_X(x) = \frac{dF_X(x)}{dx}$$

If $F_X(x)$ is piecewise constant with a countable number of discontinuities then X is said to be a discrete random variable. For discrete random variables we will use their probability mass function

$$p_X(x) \stackrel{\Delta}{=} P\{X = x\}$$

Expectation of a Random Variable

The expectation of a continuous random variable is

$$E[X] = \int_{-\infty}^{\infty} x f_X(x) dx$$

The expectation of a discrete random variable is

$$E[X] = \sum_{x: p_X(x) \neq 0} x p_X(x)$$

If X_1, X_2, \ldots, X_n are random variables the joint distribution $F_n(x_1, \ldots, x_n)$ is defined as

$$F_n(x_1,\ldots,x_n)=P\{X_1\leq x_1,\ldots,X_n\leq x_n\}$$

If these random variables are (jointly) continuous then their joint density $f_n(x_1, \ldots, x_n)$ is defined as

$$f_n(x_1,\ldots,x_n) = \frac{\partial^n F_n(x_1,\ldots,x_n)}{\partial x_1\ldots\partial x_n}$$

If these random variables are discrete then the joint probability mass function is

$$p_n(x_1,...,x_n) = P\{X_1 = x_1,...,X_n = x_n\}$$

A complex random variable is a function from Ω to C (d is the set of complex numbers)

$$X: \Omega \to C$$

such that $\{\Re X \leq x_r, \Im X \leq x_i\} \in \mathcal{F} \ \forall x_r, x_i \in R$

$$X(w) = \operatorname{Re}(X(w)) + j \operatorname{Im}(X(w)).$$

Useful Bounds

1) Union Bound:

$$P(A \cup B) \leq P(A) + P(B)$$

$$P\left(\bigcup_{i=1}^{M} A_i\right) \leq \sum_{i=1}^{M} P(A_i)$$

2) Chebyshev Bound: Let $m_X = E[X]$ and $\sigma_X^2 = E[(X - m_X)^2]$ then

$$P\{|X-m_X|\geq \delta\}\leq \frac{\sigma_X^2}{\delta^2}.$$

Proof:

$$\sigma_x^2 = \int_{-\infty}^{\infty} (x - m_X)^2 f_X(x) dx$$

$$\geq \int_{|x - m_X| \ge \delta} (x - m_X)^2 f_X(x) dx$$

$$\geq \delta^2 \int_{|x - m_X| \ge \delta} f_X(x) dx$$

$$= \delta^2 P\{|X - m_X| \ge \delta\}$$

3) Chernoff Bound:

$$P\{X \ge u\} \le e^{-su} E[e^{sX}], \quad s \ge 0$$

Proof:

Let
$$g(x) = \begin{cases} 1, & x \ge u \\ 0, & x < u \end{cases}$$

Since $s \ge 0$

$$g(x) \le e^{s(x-u)}$$

Thus

$$P\{X \ge u\} = \int_u^\infty f_X(x)dx = \int_{-\infty}^\infty g(x)f_X(x)dx$$
$$= E[g(X)]$$
$$\le E[e^{s(X-u)}] = e^{-su} E[e^{sX}].$$

Example: Let X_1, \ldots, X_n be random variables. Let H_0 and H_1 be two events. Let $p_0(x_1, \ldots, x_n)$ be the conditional density function of X_1, \ldots, X_n given H_0 and $p_1(x_1, \ldots, x_n)$ be the conditional density function of X_1, \ldots, X_n given H_1 . Find a bound on

$$P_{e} = P\{p_{1}(X_{1},...,X_{n}) \ge p_{0}(X_{1},...,X_{n}) | H_{0}\}$$
$$= P\{\frac{p_{1}(X_{1},...,X_{n})}{p_{0}(X_{1},...,X_{n})} \ge 1 | H_{0}\}$$
$$= P\{\ln\left(\frac{p_{1}(X_{1},...,X_{n})}{p_{0}(X_{1},...,X_{n})}\right) \ge 0 | H_{0}\}$$

Let $Y = \ln \frac{p_1(\underline{X})}{p_0(\underline{X})}$

$$P_e = P\{Y \ge 0 | H_0] \le E[e^{sY} | H_0]$$
$$= \int_{\mathbb{R}^n} \exp\left[s \ln \frac{p_1(\underline{x})}{p_0(\underline{x})}\right] p_0(\underline{x}) d\underline{x}$$

A random variable is Gaussian if the density function is

$$p_X(x) = \frac{1}{\sqrt{2\pi\sigma}} \exp\{-\frac{1}{2\sigma^2}(x-\mu)^2\}$$

where μ is the mean and σ^2 is the variance. The characteristic function of a random variable X is defined as $\phi_X(s) = E[e^s X]$. For a Gaussian random variable the characteristic function is

$$\phi_X(s) = e^{\frac{s^2\sigma^2}{2} + \mu s}$$

Def: A function $g : \mathbb{R}^N \to \mathbb{R}$ is said to be concave (convex \cap) if for any $\underline{x}_1 \in \mathbb{R}^n, \underline{x}_2 \in \mathbb{R}^n$ and $0 < \theta < 1$

$$\Theta g(\underline{x}_1) + (1 - \Theta)g(\underline{x}_2) \le g(\Theta \underline{x}_1 + (1 - \Theta)\underline{x}_2)$$

where the vector addition is component-wise addition.

A function $g: \mathbb{R}^n \to \mathbb{R}$ is said to be convex (convex \cup) if

$$\Theta g(\underline{x}_1) + (1 - \theta)g(\underline{x}_2) \ge g(\Theta \underline{x}_1 + (1 - \Theta)\underline{x}_2)$$

Jensen's Inequality: If f(x) is a concave (convex \cap) function mapping $\mathbb{R}^n \to \mathbb{R}$ then

 $E[f(\underline{X})] \le f(E[\underline{X}]).$

If f(x) is a convex (convex \cup) function mapping $\mathbb{R}^n \to \mathbb{R}$ then

$$E[f(\underline{X})] \ge f(E[\underline{X}]).$$

Proof for discrete random variables: (By induction) Let <u>X</u> take on values $\underline{x_1}, \underline{x_2}$, with nonzero probability

$$E[f(\underline{X})] = p(\underline{x}_1)f(\underline{x}_1) + p(\underline{x}_2)f(\underline{x}_2)$$

$$\leq f(p(\underline{x}_1)\underline{x}_1 + p(\underline{x}_2)\underline{x}_2)$$

$$= f(E[\underline{X}])$$

where the first inequality is due to the definition of convexity. Assume if \underline{X} is discrete taking values

$$\underline{x}_1, \dots, \underline{x}_{n-1} \text{ then } \sum_{i=1}^{n-1} p(\underline{x}_i) = 1$$
$$\sum_{i=1}^{n-1} p(\underline{x}_i) f(\underline{x}_i) \leq f\left(\sum_{i=1}^{n-1} p(\underline{x}_i) f(x_i)\right)$$

Now let \underline{X} take values $\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n$

$$\begin{split} E[f(\underline{X})] &= \sum_{i=1}^{n} p(\underline{x}_i) f(\underline{x}_i) = \sum_{i=1}^{n-1} p(\underline{x}_i) f(\underline{x}_i) + p(\underline{x}_n) f(\underline{x}_n) \\ \text{Let } \alpha &= \sum_{j=1}^{n-1} p(\underline{x}_j) \\ E[f(\underline{X})] &= \alpha \sum_{i=1}^{n-1} \frac{p(\underline{x}_i)}{\alpha} f(\underline{x}_i) + p(\underline{x}_n) f(\underline{x}_n) \\ &\qquad \sum_{i=1}^{n-1} \frac{p(\underline{x}_i)}{\alpha} = 1 \\ E[f(\underline{X})] &\leq \alpha f\left(\sum_{i=1}^{n-1} \frac{p(\underline{x}_i)}{\alpha} \underline{x}_i\right) + p(\underline{x}_n) f(\underline{x}_n) \\ &\leq f\left(\sum_{i=1}^{n-1} p(\underline{x}_i) \underline{x}_i + p(\underline{x}_n) \underline{x}_n\right) \\ &= f\left(\sum_{i=1}^{n} p(\underline{x}_i) \underline{x}_i\right) \end{split}$$

Let X_1, \ldots, X_n be a random vector. The covariance matrix of X_1, \ldots, X_n is defined to be

$$K_X = \begin{bmatrix} K_{1,1} & K_{1,2} & \dots & K_{1,n} \\ K_{2,1} & & \ddots & \\ & \ddots & & \\ & K_{n,1} & & K_{n,n} \end{bmatrix}.$$

where

$$K_{i,j} = E[(X_i - \mu_i)(X_j - \mu_j)^*]$$

and

$$\mu_i = E[X_i]$$

Def: A $n \times n$ matrix is said to be nonnegative definite if for any vector (a_1, \ldots, a_n)

$$\sum_{i=1}^{n} \sum_{j=1}^{n} a_i k_{i,j} a_j^* \ge 0 \quad \text{and} \quad \text{real}$$

i.e.,

$$\mathbf{a}K_{\mathbf{X}}\mathbf{a}^T \geq 0$$
 and real.

(positive definite if strict inequality holds).

Claim: The covariance matrix is always nonnegative definite. **Proof:**

$$\sum_{i=1}^{n} \sum_{j=1}^{n} a_{i}k_{ij}a_{j}^{*}$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{n} a_{i}E[(X_{i} - \mu_{i})(X_{j} - \mu_{j})^{*}]a_{j}^{*}$$

$$= E\left[\sum_{i=1}^{n} \sum_{j=1}^{n} a_{i}(X_{i} - \mu_{i})a_{j}^{*}(X_{j} - \mu_{j})^{*}\right]$$

$$= E\left[\sum_{i=1}^{n} a_{i}(X_{i} - \mu_{i})\sum_{j=1}^{n} a_{j}^{*}(X_{j} - \mu_{j})^{*}\right]$$

$$= E\left[\left|\sum_{i=1}^{n} a_{i}(X_{i} - \mu_{i})\right|^{2}\right] \ge 0$$

Let X_1, \ldots, X_n be a real random vector. The characteristic function of X_1, X_2, \ldots, X_n is defined as

$$\Psi_{X_1,\ldots,X_n}(\mathbf{v}_1,\ldots,\mathbf{v}_n)=E\left[\exp\left(j\sum_{i=1}^n\mathbf{v}_iX_i\right)\right].$$

Def: The random vector X_1, \ldots, X_n is said to be jointly Gaussian if the characteristic function of X_1, \ldots, X_n is

$$\Psi_{X_1,\ldots,X_n}(\mathbf{v}_1,\ldots,\mathbf{v}_n) = \exp\{j\underline{\mathbf{v}}^T\underline{\boldsymbol{\mu}} - \frac{1}{2}\,\underline{\mathbf{v}}^T K\underline{\mathbf{v}}\}$$

where $v^T = (v_1, \dots, v_n)$, $\mu^T = (\mu_1, \dots, \mu_n)$ and *K* is a real symmetric nonnegative definite $n \times n$ matrix. If *K* is *positive* definite then the joint density of X_1, \dots, X_n is

$$p(\mathbf{x}) = (2\pi)^{-1/2} (\det K)^{-1/2} \exp\{-1/2(\mathbf{x} - \underline{\mu})^T K^{-1}(\underline{x} - \mu)\}.$$

Fact: Let **X** be a random *n* vector. Then **X** is jointly Gaussian iff **X** can be expressed as $W\mathbf{Y} + \mu$ where $\mu = (\mu_1, \dots, \mu_n) \in \mathbb{R}^n$, *W* is and $n \times n$ matrix and Y_1, \dots, Y_n are independent mean zero Gaussian random variables (the matrix *W* can be taken to be orthogonal, i.e. the rows of *W* are orthogonal).

$$K_x = W K_Y W^T$$
.

Now let **X** be a jointly Gaussian random vector (of length *n*) with mean μ covariance matrix *K*. Let *F* be a *n* by *n* matrix. Consider the random variable

$$Y = \mathbf{X}F\mathbf{X}^T$$

We would like to be able to determine the density function of this random variable. Instead, we will determine the characteristic function of this random variable. The characteristic function is

$$\Psi_Y(\mathbf{v}) = E[\exp(j\mathbf{v}Y)]$$

=
$$\frac{\exp\{j\mathbf{v}\mu^T(F^{-1}-2j\mathbf{v}K)^{-1}\mu\}}{\det(I-2j\mathbf{v}KF)}$$

For example, let n = 1, then $K = \sigma^2$ and

$$\Psi_Y(\mathbf{v}) = \frac{\exp\{j\mathbf{v}\mu^2 F/(1-2j\mathbf{v}\sigma^2 F)\}}{(1-2j\mathbf{v}\sigma^2 F)}.$$

Inverting this yields the Rician distributed random variable. For v = -js, F = 1 the characteristic function becomes

$$E[\exp(sY)] = E[\exp(sX^2)] = \frac{\exp\{s\mu^2/(1-2s\sigma^2)\}}{(1-2s\sigma^2)}.$$

provided that $\operatorname{Re}[s] < 1/2\sigma^2$.

2. Random Processes

Def: A random process $\{X(t); t \in T\}$ is an indexed collection of random variables (i.e. for each $t \in T$, the index set, X(t) is a random variable).

Def: The covariance function of a random process $\{X(t); t \in T\}$ is defined as

$$K(s,t) = E[(X(s) - \mu(s))(X(t) - \mu(t))^*]$$

where $\mu(t) = E[X(t)]$.

Def: A function $K(s,t) : R \times R \to R$ is said to be nonnegative definite if for any $n \ge 1$ and time instants t_1, \ldots, t_n and any function a(t)

$$\sum_{i=1}^{n} \sum_{j=1}^{n} a(t_i) K(t_i, t_j) a^*(t_j) \ge 0 \text{ (and is real)}$$

(positive definite if strict equality holds). Equivalently $\int \int a(t)K(t,s)a^*(s)dtds \ge 0$ and is real.

Claim: The covariance function is a nonnegative definite function.

Def: A random process is said to be Gaussian if for any *n* and time instances $t_1, \ldots, t_n, X(t_1), \ldots, X(t_n)$ is jointly Gaussian.