

### Fall 2015 EECS 578 Correct Operation for Processors and Embedded Systems

### **Introduction & Motivation**

- An error-tolerant system is in urgent need to eliminate various external factors that can cause errors in modern techniques. A single transient fault may cause the whole system to perform erroneously. Unreliability in systems can lead to huge loss.
- Stochastic logic can create analog signal states in digital-based systems. It can be regarded as "bit-level" redundancy in some sense.
- $\blacktriangleright$  Stochastic arithmetic can be adapted to computing such as image processing due to a number of features
  - + Tolerant transient fault
  - + Simple hardware in some computing
  - + Low silicon area and faster clock period
  - + progressive precision
  - More clock cycles to compute



### **Performance and Area**

- We synthesized and evaluated speed/area of conventional and stochastic designs. The clock period and area of stochastic design are both smaller than baseline design.
- $\blacktriangleright$  The stochastic logic itself is only a small portion of the area. The most area is used to covert between regular number and stochastic number.
- $\blacktriangleright$  The stochastic design will need more cycles to execute.
- The *Period* \* *Area* \* #*Cycle* is roughly the same magnitude for baseline and stochastic design (if we only consider the core module).

	Baseline	Stochastic Low-Pass	Stochastic (core only) Low-Pass	Stochastic High-Pass	Stochastic (core only) High-Pass
Clock Period (ns)	7.8	1.8	1.8	1.8	1.8
Synthesis Area $(\mu m^2)$	49,687	26,796	1,063	31,222	1,461
Total Cycle	Ν	$N \cdot 2^8$	$N\cdot 2^8$	$N \cdot 2^8$	$N \cdot 2^8$
Period*Area* #Cycle	387,559N	12,347,596N	489, 830N	14,387,097N	673,228N

# **Error-Tolerant Image Processing Application Based on Stochastic Logic** Yulin Shi, Yilei Xu, Yunkai Zhao, Yue Zheng







### **Error Tolerance**

 $\blacktriangleright$  We randomly flipped the input of the filters at different error rates to see the behavior.

We use SSIM (Structural SIMilarity) and PSNR(the peak signal-tonoise ratio) to measure the similarity of pictures quantitatively.

 $\blacktriangleright$  Data shown below is the average results of ten different pictures.

L	SSIM			PSNR (dB)					
	Baseline	Stochastic	Difference	Baseline	Stochastic	Difference			
High-Pass Filter									
1%	0.407	0.447	9.83%	0.945	4.046	3.101			
5%	0.174	0.205	17.82%	-5.504	-3.728	1.776			
10%	0.106	0.146	37.74%	-7.859	-6.245	1.614			
15%	0.076	0.118	55.26%	-8.854	-7.476	1.378			
Low-Pass Filter									
1%	0.794	0.926	16.62%	25.732	33.273	7.541			
5%	0.497	0.781	57.14%	17.482	21.497	4.015			
10%	0.368	0.686	86.41%	13.310	15.871	2.561			
15%	0.308	0.621	101.62%	10.960	12.894	1.934			



grayscale

### Discussion

 $\blacktriangleright$  The high-pass filter is more prone to faults • Low-pass filter will smooth the picture and tolerant errors to some extents ➢ Progressive precision • Partial bit-stream provide a good estimate of the exact value

Possible random number resource to reduce hardware cost









- $\blacktriangleright$  The stochastic logic filter can be adapted to image processing filters to simplify the hardware design.
- F It consumes less silicon area and can operate at a faster clock While it will take more cycle numbers than conventional filter to execute, stochastic logic takes advantage of randomness and outperforms the baseline filter in terms of the error-tolerance capability.

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