

# High-Resolution Analysis of Least Distortion of Fixed-Rate Vector Quantizers

## Zador's Formula

- Begin with Bennett's Integral

$$D \cong \frac{1}{M^{2/k}} \int \frac{m(\underline{x})}{\lambda^{2/k}(\underline{x})} f_X(\underline{x}) d\underline{x}$$

- Find best inertial profile
- Find best point density
- Substitute into Bennett's integral to obtain high-resolution approximation to the OPTA function of k-dimensional VQ.

Z-1

## Best Inertial Profile

- For any dimension k and probability distribution, the best inertial profile is a constant. The constant is independent of the source probability distribution.
- Sketch of the proof: (no rigorous proof exists)
  - Claim 1: When the source random vector is uniformly distributed on a k-dimensional cube, the best inertial profile is a constant. That is the inertial profile of an optimal quantizer is, approximately, a constant.  
Let  $m_k^*$  denote the constant.  
(Actually, one can replace "cube" with "sphere" or any other sufficiently nice convex region.)

Z-2

- Claim 2: For any k-dimensional probability density function, the best inertial profile is the constant  $m_k^*$ . That is, an optimal quantizer with many points has  $m(\mathbf{x}) = m_k^*$ .

Z-3

### Gershho's Conjecture:

- When  $M$  is large, most cells of an optimal, k-dimensional, M-point, fixed-rate quantizer are approximately congruent to some basic cell shape.
- The basic cell shape is the k-dimensional tessellating polyhedron with least NMI.
- In most small regions, the quantizer partition is a "tessellation" based on this basic cell shape.

A cell "tesselates" or "tiles" if there exists a partition of  $R^k$  with each cell being a translation or rotation (but not a scaling) of the basic cell shape.

- $m_k^* =$  least nmi of any tessellating k-dimensional polyhedron  
 $=$  Gershho's constant

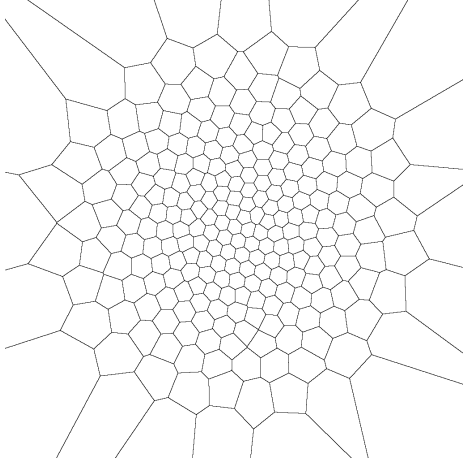
Notes:

- Since the optimal quantizer will ordinarily have cells of different sizes, its partition will not be a tessellation. However, in small regions the tessellation will be apparent, i.e. locally it is approximately a tessellation.
- The tessellation generated by the basic cell shape might even be a "lattice", meaning that all cells of the tessellation are translations (rather than rotations) of one another.
- We will assume Gershho's conjecture is correct when we need the value of  $m_k^*$ . If this is not exactly correct, it is not off by much.

Z-4

**Example:**

A two-dimensional VQ with  $M = 256$  designed by the LBG algorithm for an IID Gaussian source.



**Best Point Density**

Assuming the best inertial profile is a constant, we need to find the point density minimizing the remaining part of Bennett's integral.

$$\int \frac{f_{\mathbf{x}}(\mathbf{x})}{\lambda^{2/k}(\mathbf{x})} d\mathbf{x} \quad (*)$$

It could be found with calculus of variations, but we will use Holder's inequality.

Holder's inequality:

Given function's  $f$  and  $g$ , then for any  $q, r > 0$  such that  $\frac{1}{q} + \frac{1}{r} = 1$ ,

$$\int |f(\underline{x}) g(\underline{x})| d\underline{x} \leq \left( \int |f(\underline{x})|^q d\underline{x} \right)^{1/q} \left( \int |g(\underline{x})|^r d\underline{x} \right)^{1/r}$$

with equality iff for some  $c$ ,  $|f(\underline{x})|^q = c |g(\underline{x})|^r$ , all  $\underline{x}$

Strategy: Choose  $f, g, q$  and  $r$  so that

$$|f(\underline{x})|^q = \frac{f_{\underline{x}}(\underline{x})}{\lambda(\underline{x})^{2/k}} \quad \text{and} \quad \int |g(\underline{x})|^r d\underline{x} = 1.$$

Then

$$\int \frac{f_{\underline{x}}(\underline{x})}{\lambda(\underline{x})^{2/k}} d\underline{x} = \int |f(\underline{x})|^q d\underline{x} \geq \left( \int |f(\underline{x}) g(\underline{x})| d\underline{x} \right)^q \left( \int |g(\underline{x})|^r d\underline{x} \right)^{q/r} = \left( \int |f(\underline{x}) g(\underline{x})| d\underline{x} \right)^q$$

with equality iff there is constant  $c$  such that  $|f(\underline{x})|^q = c |g(\underline{x})|^r$ .

If it turns out that the last integral does not depend on  $\lambda$ , then we have a lower bound to the integral we are minimizing. And we can minimize the integral by choosing  $\lambda$  to satisfy the condition that gives equality in the lower bound.

Z-7

Our choices:

$$q = \frac{k+2}{k}, \quad r = \frac{k+2}{2} \quad \Rightarrow \quad \frac{1}{q} + \frac{1}{r} = \frac{k}{k+2} + \frac{2}{k+2} = 1$$

$$f(\underline{x}) = \left( \frac{f_{\underline{x}}(\underline{x})}{\lambda^{2/k}(\underline{x})} \right)^{k/(k+2)} \quad \text{and} \quad g(\underline{x}) = \lambda^{2/(k+2)}(\underline{x})$$

Then as desired,  $|f(\underline{x})|^q = \frac{f_{\underline{x}}(\underline{x})}{\lambda^{2/k}(\underline{x})}$  and  $\left( \int |g(\underline{x})|^r d\underline{x} \right)^{q/r} = \left( \int \lambda(\underline{x}) d\underline{x} \right)^{q/r} = 1$

Therefore,  $\int \frac{f_{\underline{x}}(\underline{x})}{\lambda^{2/k}(\underline{x})} d\underline{x} \geq \left( \int |f(\underline{x}) g(\underline{x})| d\underline{x} \right)^q = \left( \int f_{\underline{x}}^{k/(k+2)}(\underline{x}) d\underline{x} \right)^{(k+2)/k}$

where, fortunately, the right-hand side does not depend on  $\lambda$ , and where equality holds iff there is a constant  $c$  such that

$$\frac{f_{\underline{x}}(\underline{x})}{\lambda^{2/k}(\underline{x})} = c \lambda(\underline{x}), \quad \text{i.e.} \quad \lambda(\underline{x}) = c' \frac{f_{\underline{x}}^{k/(k+2)}(\underline{x})}{\lambda^{2/k}(\underline{x})}$$

where  $c'$  is chosen to make  $\lambda(\underline{x})$  integrate to one. We conclude that the integral (\*) is minimized by the point density

$$\lambda_k^*(\underline{x}) = \frac{f_{\underline{x}}^{k/(k+2)}(\underline{x})}{\int f_{\underline{x}}^{k/(k+2)}(\underline{x}') d\underline{x}'}$$

and the resulting minimum value is  $\left( \int f_{\underline{x}}^{k/(k+2)}(\underline{x}) d\underline{x} \right)^{(k+2)/k}$

Z-8

Substituting  $\lambda_k^*$  and  $m_k^*$  into Bennett's integral yields:

### Zador's Theorem (Zador, 1963)

When  $M$  is large, the least distortion of fixed-rate,  $k$ -dim'l VQ with  $M$  points is

$$\delta(k,M) \cong \sigma^2 \beta_k m_k^* \frac{1}{M^{2/k}} \triangleq Z(k,M)$$

where  $Z(k,M)$  is called Zador's function

$$\sigma^2 = \text{source variance} = \frac{1}{k} \sum_{i=1}^k \text{variance}(X_i)$$

$$\beta_k = \frac{1}{\sigma^2} \left( \int f_{\underline{X}}(x)^{k/(k+2)} dx \right)^{(k+2)/k} = \text{"Zador's factor"}$$

depends on "shape" of  $f_{\underline{X}}(x)$ ; invariant to a scaling)

$m_k^*$  = least NMI of  $k$ -dim'l tessellating polytopes (we assume)

### Equivalent Statements

When  $R$  is large, the best fixed-rate,  $k$ -dimensional VQ's with rate  $R$  have MSE

$$\delta(k,R) \cong \sigma^2 \beta_k m_k^* 2^{-2R} \triangleq Z(k,R)$$

When  $R$  is large, the best fixed-rate,  $k$ -dimensional VQ's with rate  $R$  have SNR

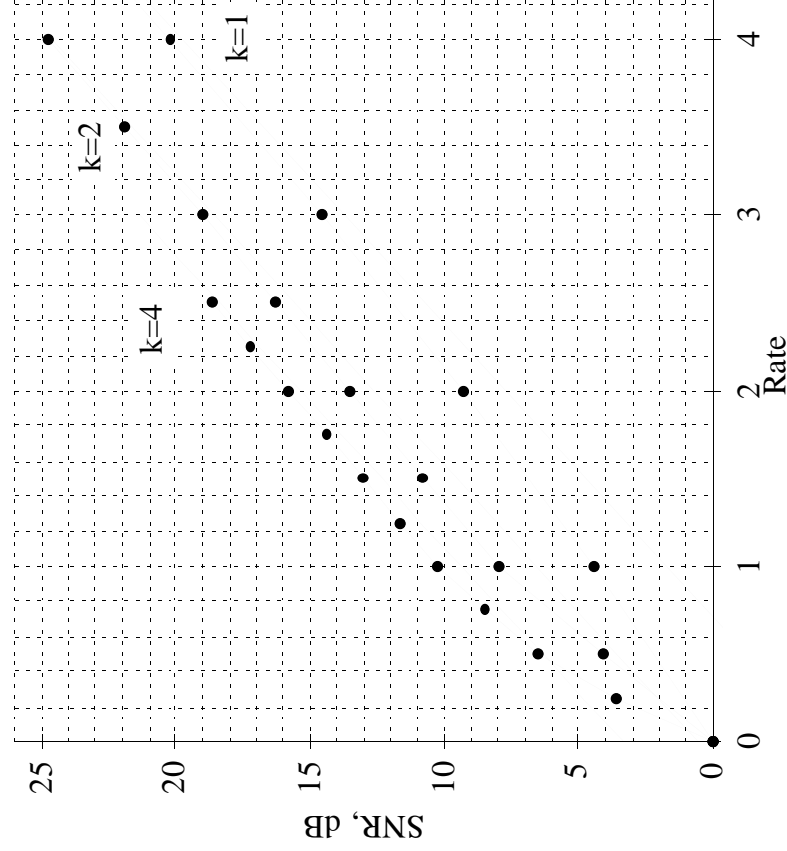
$$S(k,R) \cong 10 \log_{10} \frac{\sigma^2}{Z(k,R)} = 6.02 R - 10 \log_{10} m_k^* \beta_k$$

Note: SNR increases at 6 dB per bit for optimal quantizers.

Z-9

How large must  $M$  or  $R$  be in order for the formulas to be accurate?

Example: Gauss-Markov Source, corr. coeff.  $\rho = .9$



VQ's designed by LBG algorithm.

Straight lines are Zador's function  $Z(k,R)$ .

$m_4^*$  is estimated.

Z-10

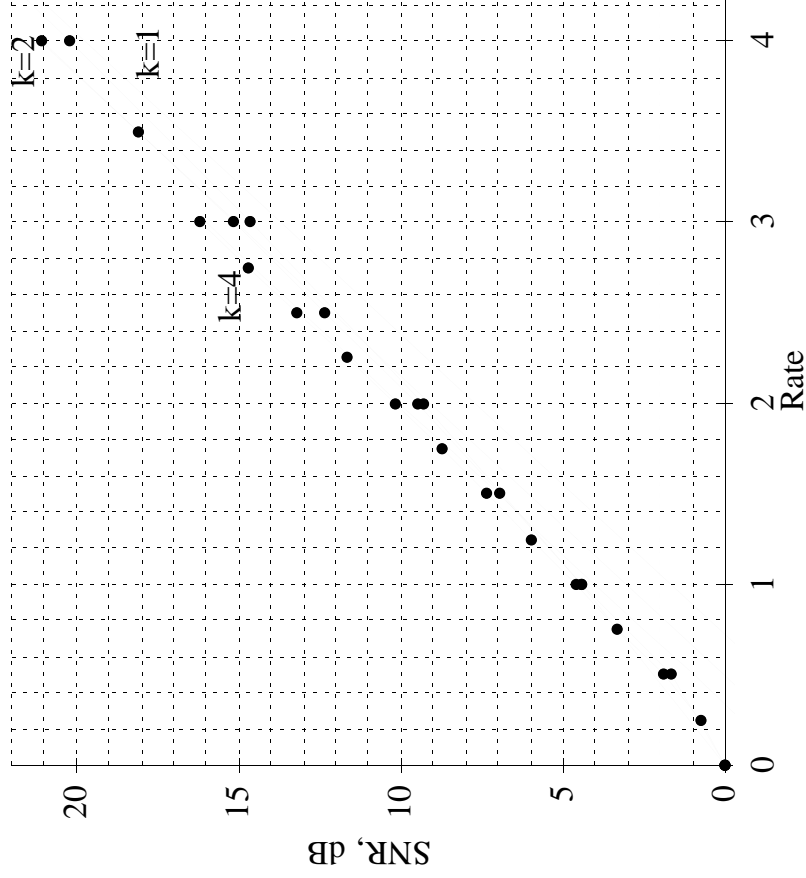
Data for the previous plot

Gauss-Markov Source,  $\rho = .9$ , SNR's in dB

Rate	k = 1		k = 2		k = 4	
	Act'l	Pred'd	Act'l	Pred'd	Act'l	Pred'd
0.0	0.0	-4.35	0.0	0.6	0.00	3.33
0.5			4.0	3.6	6.55	6.34
1.0	1.68	4.4	7.9	6.6	10.22	9.35
1.5			10.8	9.6	13.04	12.36
2.0	7.70	9.3	13.5	12.6	15.81	15.37
2.5			16.3	15.6	18.66	18.38
3.0	13.72	14.62	19.0	18.6		
3.5			21.9	21.6		
4.0	19.74	20.22	24.8	24.6		

The predicted value at  $R = 0$  is  $-10 \log_{10} m_k^* \beta_k$

Example 2: IID Gaussian Source



VQ's designed by LBG algorithm.

Straight lines are from Zador's function  $Z(k, R)$ .

$m_4^*$  is estimated.

Data for the previous plot  
IID Gaussian Source, SNR's in dB

Rate	k = 1		k = 2		k = 4				
	Act'l	Pred' d	Diff.	Act'l	Pred' d	Diff.	Act'l	Pred' d	Diff.
0.0	0.0	-4.35	4.35	0.00	-2.95	2.95	0.00	-2.01	2.01
0.5				1.66	0.06	1.60	1.89	1.00	0.89
1.0	1.68	4.4	2.72	4.39	3.07	1.32	4.60	4.01	0.60
1.5				6.96	6.08	0.88	7.34	7.02	0.32
2.0	7.70	9.3	1.60	9.64	9.09	0.55	10.18	10.03	0.15
2.5				12.42	12.10	0.32	13.21	13.04	0.17
3.0	13.72	14.62	0.90	15.27	15.11	0.16	16.18	16.05	0.14
3.5				18.17	18.12	0.05			
4.0	19.74	20.22	0.48	21.12	21.13	-0.01			

The predicted value at  $R = 0$  is  $-10 \log_{10} m_k^* \beta_k$