

| | | |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| COURSE: EECS 460. TITLE: Control Systems Analysis and Design. PREREQUISITES: EECS 306 or Graduate standing. | | ELECTIVE. |
| TEXTBOOK: J. Kuo and Golnaraghi, <i>Automatic Control Systems</i> , 8 th ed., Wiley | | |
| CATALOG DESCRIPTION: Basic techniques for analysis and design of controllers applicable in any industry (e.g. automotive, aerospace, computer, communication, chemical, bioengineering, power, etc.) are discussed. Both time- and frequency-domain methods are covered. Root locus, Nyquist and Bode plot-based techniques are outlined. Computer-based experiment and discussion sessions are included in the course. | | |
| COURSE OBJECTIVES: | | TOPICS COVERED: |
| <ol style="list-style-type: none"> 1. To teach students basic concepts of steady-state and transient analysis of linear feedback systems; 2. To teach students basic concepts of robustness of linear feedback systems; 3. To teach students techniques and CAD tools for designing linear feedback control systems; 4. To stimulate student interest in control applications, & to prepare them for industry & graduate study | | <ol style="list-style-type: none"> 1. Transfer functions, Mason gain 2. Steady state response: tracking 3. Transient response: rise time, overshoot, stability (Routh table) 4. Root locus; use PID & lead-lag 5. Nyquist plot; closed-loop stable 6. Bode plots; Bode compensation 7. Time delays, non-minimum phase zeros, two degree of freedom designs |
| COURSE OUTCOMES [Program Outcomes Addressed] | | ASSESSMENT (Course outcomes) |
| <ol style="list-style-type: none"> 1. Ability to design a controller so that a feedback systems meets steady-state and transient specs; [1,3,11] 2. Ability to design a controller so that a feedback systems meets robustness specs; [1,3,11] 3. Ability to recognize feedback problems that are fundamentally difficult; [1,3,11] 4. Ability to use root locus, Nyquist and Bode techniques to modify properties of a control system; [1,11] 5. Ability to identify and evaluate design tradeoffs among specs such as rise time and robustness; [1,5,11] 6. Ability to use CAD tools (Matlab) for analysis and design of control systems. [1,3,5,11,13,14] | | <ol style="list-style-type: none"> 1. Weekly HW sets [1,2,3,4,5,6] 2. 3 in-class exams [1,2,3,4,5,6] 3. 2 software-based projects |
| PROGRAM OUTCOMES ADDRESSED: 1,3,5,11 | CLASS/LABORATORY SCHEDULE: | |
| PROFESSIONAL COMPONENT ADDRESSED: 13,14 | | |
| PREPARED BY: Andrew E. Yagle on Nov. 25, 2004 | | |

COURSE DESCRIPTION: University of Michigan, College of Engineering, ELECTRICAL ENGINEERING PROGRAM