```
EECS 373 - Homework #3 & Practice Exam - Solution Key
Prabal Dutta
1. Fill-in-the-blank or circle the best answer
  a. R0; R14 or LR
  b. 16-bit and 32-bit
  c.5 ns
  d. sometimes
  e. does not
  f. UART
  g. synchronous; addresses embedded in frames
  h. flip-flop
  i. grow quadratically
  j. .text (lec 2, slide 47)
2. Rewrite the add function in EABI assembly. Key things to consider are:
   a) caller (r0-r3)/callee save (r4-r11) registers
   b) parameter passing (r0-r3) and return (r0/r0+r1)conventions
   c) assigning variable registers: r4-r8, r10, r11 (r9 is special)
   d) dealing with the link register: LR (r15)
   Notes:
   - a is passed in r0 (this is the a pointer to a[0])
   – n is passes in r1
   - Must push/pop LR since add is not a leaf function

    Need storage for local variables i and sum

   - Must save/restore r0-r3, if live, across call to printint(sum)
   - Don't need i after printint, so we can put it in r2 and skip save/restore
   - Need to either save/restore sum across printint call or put it in a
     callee save register. If we save and restore, that's (another)
     push/pop memory access (in addition to the LR), so we might as
     well just push/pop a callee save register (e.g. r4)
   - Must return sum in r0
   - Putting all this into an assembly function gives us:
     a in r0
     n in r1
     i in r2
     sum in r4
     sum in r0 (for call to printint)
sum in r0 (for return value)
add: push {r4, lr}
                       ; r0 = a, r1 = n
      mov r2, #0
                       ; r^2 = i = 0
      mov r4, #0
                       ; r4 = sum = 0
                        ; r2-r1
loop: cmp r2, r1
                       ; branch to done when i>=n
      bge done
           r3, [r0, r2, lsl#2] ; load r3 with value of mem[r0+r2*4] r4, r4, r3 ; sum += a[i]
      ldr
      add
           r2, #1
                       ; i++
      add
           loop
      b
                       ; iterate loop
done: mov
                       ; prepare to pass sum to printint in r0
           r0, r4
           printint
                       ; call printint
      bl
                       ; restore r0 as printint might have clobbered it
      mov
           r0, r4
                       ; restore r4 and load pc with original value of lr
      pop \{r4, pc\}
3. ARM Assembly
  a. 0b 0100 0100 1101 1001 = 0x44D9
  b. The key here is:
     i) Remembering your addressing modes:
       [<Rn>, <offset>] - Offset: EA = <Rn> + <offset>
       [<Rn>, <offset>]! - Pre-idx: EA = <Rn> + <offset>; <Rn> += <offset>
       [<Rn>], <offset> - Post-indexed: EA = <Rn>; <Rn> += <offset>
     ii) Paying attention to whether ld and str size (byte, halfword, word)
       str - stores a word (32 bit)
```

```
ldrb - loads a byte (8 bits)
     strh - stores a half word (16 bits)
     ldr – loads a word (32 bit)
   r1 = 0 \times 00000 FFE
   r2 = 0 \times DD00CCDD
   r3 = 0 \times 0000000F
c. 0 \times 1000 = 0b \ 0001 \ 0000 \ 0000 \ 0000 = 2^{12} = 4096 (msb = 0, so pos number)
   0xfffc = 0b 1111 1111 1110 (msb = 1, so neg number)
          = 0b 0000 0000 0000 0011 invert the bits
          + 0b 0000 0000 0000 0001 add one
            _____
          - 0b 0000 0000 0000 0100 = -(2^2) = -4
   0xffff = 0b 1111 1111 1111 1111 (msb = 1, so neg number)
          = 0b 0000 0000 0000 0000 invert the bits
          + 0b 0000 0000 0000 0001 add one
          - 0b 0000 0000 0000 0001 = -(2^0) = -1
```

4. Memory mapped I/0.

- a. // Declare reg and add 7 to REG_F00's value uint32_t* reg = (uint32_t*)REG_F00; *reg += 7;
- b. Sketch glue logic to interface DFF to APB



Note: The APB *spec* doesnt say anything about whether tristate buffers are needed (and if your bus is multiplexed, it's not). But, to demonstrate the importance of only driving the bus when you (and you alone) are being read, it's useful to add the tristate driver.

Note: Drawn using asciiflow.com

5. Serial busses

- a. v(t) = Vcc (1 e^(-t/T)
 t = -R*C*ln(1-v(t)/Vcc) [at (v(t) = 2.4V)
 t = -(10e3)(50e-12)(ln(1-2.4/3.0))
 t = 0.8 us
- b. There are 8 data bits for 20 bits transmitted, giving 40% data throughput. With four different devices, each will get 1/4 of the this overall throughput, giving each device 10% of the data

throughput, of 400 kHz * 1 bit/Hz * 10% = 40 kbps/device.

6. Logic Design



8. Enable Interrupts. The challenge here is to map the interrupt humber x to the particular memory word and bit offset. First, note that a word has 32 bits, so interrupts 0–31 map to the word at 0xE000E1000, and interrupts 32–63 map to the word at 0xE000E1004, and so on. So, to determine the "word," we can divide x by 32 (or, equivalently, shift if by 5 bits). To get the bit position within that word, we actually need to extract the bottom 5 bits of x which contain the a value in the range 0–31 and turn that 5-bit value into a bit mask with the appropriate bit set. Finally, we just need to set the bit that corresponds to that value by writing the mask value into the appropriate register. Note one really important thing: we *don't* need to read, update, and write back the ISER registers because the only thing that matters is writing 1s to enable interrupts (i.e. writing 0s does *not* disable interrupts!). The following code snippet does all of the following.

```
void enable_interrupts(int x) {
    uint32_t base = 0xE000E100;
    uint32_t idx = x >> 5;
    uint32_t bit = x & 0x1f;
    uint32_t mask = 1 << bit;
    *((uint32_t*)(base+4*idx)) = mask;
}</pre>
```