

Error Exponent Region for Gaussian Multiple Access Channels

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I. INTRODUCTION

We introduce the notion of error exponent region (EER) for a multi-user channel. We define a probability of error for each user, which, in general may be different for different users. Therefore, there are multiple error exponents, one for each user, for a given multi-user channel. The error exponent region specifies the set of error-exponent vectors, which are simultaneously achievable by all users in the multi-user channel [1]. In this work, we derive an inner bound (achievable region) and an outer bound for the error exponent region of a Gaussian multiple access channel (GMAC).

II. FORMULATION AND MAIN RESULT

An error exponent region for a multi-user channel depends on the channel operating (rate) point. For a two-user channel, we use the notation $EER(R_1, R_2)$ to denote the EER when the channel is operated at rate pair (R_1, R_2) . Consider a GMAC

$$Y = X_1 + X_2 + Z, \quad (1)$$

where X_1 and X_2 are the channel inputs for user 1 and user 2 with $E(X_1^2) = SNR_1$, $E(X_2^2) = SNR_2$, and Z is white Gaussian noise with unit variance. Denote $E(R, SNR)$ the maximum of random coding exponent and expurgated exponent of a single-user Gaussian channel. Our main result follow.

Theorem 1: For a two-user GMAC in (1), an achievable $EER(R_1, R_2)$ (inner bound) is $EER_s(R_1, R_2) \cup EER_{td}(R_1, R_2)$, where $EER_{td}(R_1, R_2)$, achievable region using time-division, and $EER_s(R_1, R_2)$, achievable region using superposition, are

$$\begin{aligned} EER_{td}(R_1, R_2) &= \{(e_1, e_2) : 0 < \alpha < 1 \\ e_1 &\leq \alpha E\left(\frac{R_1}{\alpha}, \frac{SNR_1}{\alpha}\right), e_2 \leq (1 - \alpha) E\left(\frac{R_2}{1 - \alpha}, \frac{SNR_2}{1 - \alpha}\right)\}, \\ EER_s(R_1, R_2) &= \{(e_1, e_2) : \\ e_1 &\leq \max\{E(R_1, \frac{SNR_1}{SNR_2 + 1}), \\ \min\{E(R_1, SNR_1), E_{t3}(R_1 + R_2, SNR_1, SNR_2)\}\}, \\ e_2 &\leq \max\{E(R_2, \frac{SNR_2}{SNR_1 + 1}), \\ \min\{E(R_2, SNR_2), E_{t3}(R_1 + R_2, SNR_1, SNR_2)\}\}, \end{aligned}$$

where

$$\begin{aligned} E_{t3}(R_3, SNR_1, SNR_2) &= \max_{\rho, \theta_1, \theta_2} \{E_{t3,0}(\rho, \theta_1, \theta_2) - \rho R_3\} \\ E_{t3,0}(\rho, \theta_1, \theta_2) &= (1 + \rho) \ln \left[\frac{e\sqrt{\theta_1\theta_2}}{1 + \rho} \right] - \frac{\theta_1 + \theta_2}{2} \\ &\quad + \frac{\rho}{2} \ln \left[1 + \frac{SNR_1}{\theta_1} + \frac{SNR_2}{\theta_2} \right] \end{aligned}$$

is the type-3 error exponent, and maximization is over $0 \leq \rho \leq 1$, and $0 < \theta_1, \theta_2 \leq 1 + \rho$ [2]. \square

Theorem 2: For a two-user GMAC in (1), an $EER(R_1, R_2)$ outer bound is

$$\begin{aligned} E_1 &\leq E^{su}(R_1, SNR_1) \\ E_2 &\leq E^{su}(R_2, SNR_2) \\ \min\{E_1, E_2\} &\leq E^{su}(R_1 + R_2, SNR_1 + SNR_2), \end{aligned}$$

where $E^{su}(R, SNR)$ is any error exponent upper bound for a single-user Gaussian channel. \square

In Fig. 1(a), the solid curve is the boundary of the EER inner bound, and the dashed curve is the boundary of the EER outer bound. For a single-user Gaussian channel, an error exponent is known only for $R \geq R_{crit}$. Therefore, we can't expect to find EERs for all operating points in a GMAC. The EER inner bound and the EER outer bound are indeed tight for some operating points in a GMAC. This is shown in Fig. 1(b). The solid curve is the boundary of both the EER inner and outer bounds. The error exponent pair (E_1, E_2) in Fig. 1(b) achieves point-to-point single-user Gaussian error exponents for each user. For this operating point, each user seems to operate on a single-user Gaussian channel, instead of interfering with each other on a GMAC.

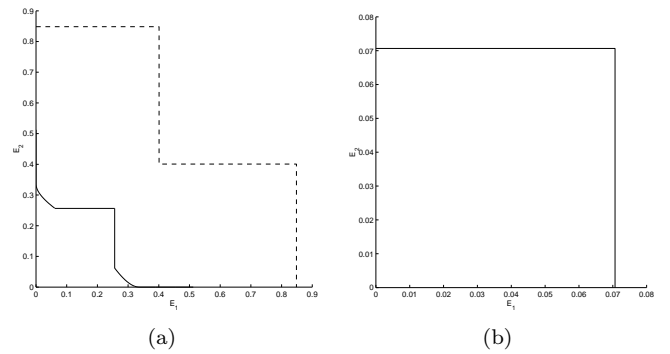


Figure 1: (a) EER inner and outer bounds ($R_1 = R_2 = 0.5$; $SNR_1 = SNR_2 = 10$). (b) EER ($R_1 = R_2 = 0.15$; $SNR_1 = SNR_2 = 1$). Inner and outer bounds are tight.

REFERENCES

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