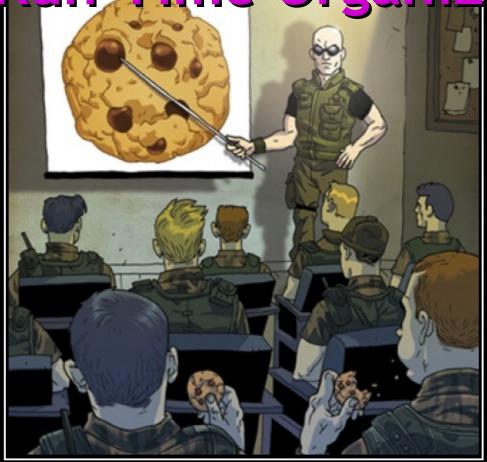
Cool Type Checking Cool Run-Time Organization



Run-Time Organization

Gentlemen, tonight we are going after the big prize. The Keeblers are paying us hansomly, but some of us might not make it back from Pepperidge farm tonight...

One-Slide Summary

- We will use SELF_TYPE_c for "C or any subtype of C". It shows off the subtlety of our type system and allows us to check methods that return self objects.
- The lifetime of an activation of (i.e., a call to) procedure P is all the steps to execute P plus all the steps in procedures that P calls.
- Lifetime is a run-time (dynamic) notion; we can model it with trees or stacks.

Lecture Outline

• SELF_TYPE

• Object Lifetime

Activation Records

Stack Frames



SELF_TYPE Dynamic Dispatch

 If the return type of the method is SELF_TYPE then the type of the dispatch is the type of the dispatch expression:

$$O,M,C \vdash e_{0} : T_{0} \rbrace A$$

$$O,M,C \vdash e_{n} : T_{n} \rbrace B$$

$$O,M,C \vdash e_{n} : T_{n} \rbrace B$$

$$M(T_{0},f) = (T_{1}',...,T_{n}', SELF_TYPE) \rbrace C$$

$$T_{i} \leq T_{i}' \qquad 1 \leq i \leq n \rbrace D$$

$$O,M,C \vdash e_{0}.f(e_{1},...,e_{n}) : T_{0}$$

Where is SELF_TYPE Illegal in COOL?

```
m(x : T) : T' \{ ... \}
```

Only T' can be SELF_TYPE! Not T.

What could go wrong if T were SELF_TYPE?

```
class A { comp(x : SELF_TYPE) : Bool {...}; };
class B inherits A {
    b() : int { ... };
    comp(y : SELF_TYPE) : Bool { ... y.b() ...}; };
...
let x : A ← new B in ... x.comp(new A); ...
...
3
```

Summary of SELF_TYPE

- The extended ≤ and lub operations do a lot of the work. Implement them to handle SELF_TYPE
- SELF_TYPE can be used only in a few places.
 Be sure it isn't used anywhere else.
- A use of SELF_TYPE always refers to any subtype in the current class
 - The exception is the type checking of dispatch, where SELF_TYPE as the return type of an invoked method might have nothing to do with the current enclosing class

Why Cover SELF_TYPE?

- SELF_TYPE is a research idea
 - It adds more expressiveness to the type system
- SELF_TYPE is itself not so important
 - except for the project
- Rather, SELF_TYPE is meant to illustrate that type checking can be quite subtle
- In practice, there should be a balance between the complexity of the type system and its expressiveness

Type Systems

- The rules in these lecture were Cool-specific
 - Other languages have very different rules
 - We'll survey a few more type systems later
- General themes
 - Type rules are defined on the structure of expressions
 - Types of variables are modeled by an environment
- Type systems tradeoff flexibility and safety

Course Goals

 At the end of this course, you will be acquainted with the fundamental concepts in the design and implementation of high-level programming languages. In particular, you will understand the **theory** and **practice** of lexing, parsing, semantic analysis, and code interpretation. You will also have gained practical experience programming in multiple different languages.

Status

- We have covered the front-end phases
 - Lexical analysis
 - Parsing
 - Semantic analysis
- Next are the back-end phases
 - Optimization (optional)
 - Code execution (or code generation)

We'll do code execution first . . .

Run-time environments

- Before discussing code execution, we need to understand what we are trying to execute
- There are a number of standard techniques that are widely used for structuring

executable code

- Standard Way:
 - Code
 - Stack
 - Heap



Run-Time Organization Outline

Management of run-time resources

- Correspondence between static (compiletime) and dynamic (run-time) structures
 - "Compile-time" == "Interpret-time"

Storage organization

Run-time Resources

 Execution of a program is initially under the control of the operating system

- When a program is invoked:
 - The OS allocates space for the program
 - The code is loaded into part of the space
 - The OS jumps to the entry point (i.e., "main")

How does "space" work?

(Digression) Virtual Memory

- An address space is a partial mapping from addresses to values. Like a big array: the value at memory address 0x12340000 might be 87. *Partial* means some addresses may be invalid.
- There is an address space associated with the physical memory in your computer. If you have 1GB of RAM, addresses 0 to 0x40000000 are valid.
- If I want to store some information on MachineX and you want to store some information on MachineX, we would have to collude to use *different* physical addresses (= different parts of the address space).

(Digression) Virtual Memory 2

- Virtual memory is an abstraction in which each process gets its own virtual address space. The OS and hardware work together to provide this abstraction. All modern computers use it.
- Each virtual address space is then mapped separately into a different part of physical memory. (simplification)
- So Process1 can store information at its virtual address 0x4444 and Process2 can *also* store information at its virtual address 0x4444 and there will be *no overlap* in physical memory.
 - e.g., P1 0x4444 virtual -> 0x1000 physical
 - and P2 0x4444 virtual -> 0x8000 physical

Program Memory Layout

Memory

Code

Other Space

Low Addresses 0x00000000

High Addresses

0x40000000

Notes

- Our pictures of machine organization have:
 - Low address at the top
 - High address at the bottom
 - Lines delimiting areas for different kinds of data
- These pictures are simplifications
 - e.g., not all memory need be contiguous
- In some textbooks lower addresses are at bottom (doesn't matter)

What is Other Space?

- Holds all data for the program
- Other Space = Data Space

- A compiler is responsible for:
 - Generating code (that is run later)
 - Orchestrating use of the data area
- An interpreter is responsible for:
 - Executing the code directly (now)
 - Orchestrating use of the (run-time) data



Code Execution Goals

- Two goals:
 - Correctness
 - Speed
- Most
 complications at
 this stage come
 from trying to be
 fast as well as
 correct



Assumptions about Execution

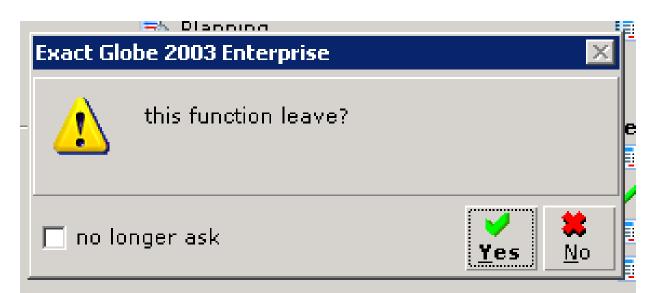
 (1) Execution is sequential; control moves from one point in a program to another in a well-defined order

 (2) When a procedure is called, control eventually returns to the point immediately after the call

Do these assumptions always hold?

Activations

- An invocation of procedure P is an activation of P
- The lifetime of an activation of P is
 - All the steps to execute P
 - Including all the steps in procedures that P calls



Lifetimes of Variables

- The lifetime of a variable x is the portion of execution during which x is defined
- Note that
 - Scope is a static concept
 - Lifetime is a dynamic (run-time) concept



Activation Trees

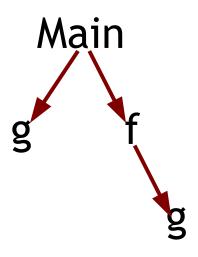
- Assumption (2) requires that when P calls Q, then Q returns before P does
- Lifetimes of procedure activations are properly nested
- Activation lifetimes can be depicted as a tree







```
Class Main {
   g(): Int { 1 };
   f(): Int { g() };
   main(): Int {{ g(); f(); }};
}
```



```
Class Main {
  g(): Int { 1 };
  f(x:Int): Int {
     if x = 0 then g() else f(x - 1) fi
  main(): Int {{ f(3); }};
```

What is the activation tree for this example?

Notes

 The activation tree depends on run-time behavior

 The activation tree may be different for every program input

- Since activations are properly nested, a stack can track currently active procedures
 - This is the call stack

```
Class Main {
  g(): Int { 1 };
  f(): Int { g() };
  main(): Int {{ g(); f(); }};
                    Main
                                         Stack
                                          Main
```

```
Class Main {
  g(): Int { 1 };
  f(): Int { g() };
  main(): Int {{ g(); f(); }};
                    Main
                                         Stack
                                          Main
```

```
Class Main {
  g(): Int { 1 };
  f(): Int { g() };
  main(): Int {{ g(); f(); }};
                    Main
                                         Stack
                                          Main
```

```
Class Main {
  g(): Int { 1 };
  f(): Int { g() };
  main(): Int {{ g(); f(); }};
                    Main
                                         Stack
                                          Main
```

Revised Memory Layout

Low Address Code Memory Stack High Address

Q: TV (110 / 842)

 Name the series and either of the characters involved in the first interracial kiss on US television. The kiss took place in the 1968 episode "Plato's Stepchildren".

Real-World Languages

 This Asian language features a relatively small vocabulary of sounds, a focus on the relative status of the speaker and listener in the conversation, three written scripts, and S-O-V ordering. Ex: 日本に行きたい。

Real-World Languages

 This Southern Athabaskan language is the most commonlyspoken Native American language north of Mexico. It has four basic vowels, two tones, inflected verbs, and was used as encryption to relay tactical secret messages in World War II.

Activation Records

- On many machines the stack starts at highaddresses and grows towards lower addresses
- The information needed to manage one procedure activation is called an activation record (AR) or frame

 If procedure F calls G, then G's activation record contains a mix of info about F and G.

What is in G's AR when F calls G?

 F is "suspended" until G completes, at which point F resumes. G's AR contains information needed to resume execution of F.

- G's AR may also contain:
 - Actual parameters to G (supplied by F)
 - G's return value (needed by F)
 - Space for G's local variables

The Contents of a Typical AR for G

- Space for G's return value
- Actual parameters
- Pointer to the previous activation record
 - The control link points to AR of F (caller of G)
 - (possibly also called the **frame pointer**)
- Machine status prior to calling G
 - Local variables
 - (Compiler: register & program counter contents)
- Other temporary values

Example 2, Revisited

```
Class Main {
  g(): Int { 1 };
  f(x:Int):Int {
     if x=0 then g() else f(x-1) (**) fi
                                  return address
  main(): Int {{f(3); (*) }};}
                                  control link
                                 argument
                      AR for f:
                                  space for
```

Stack After Two Calls to f

```
Class Main {
  g(): Int { 1 };
  f(x:Int):Int {
      if x=0 then g()
                                      result
      else f(x - 1) (**) fi
  };
                                                   Stack
  main(): Int {{f(3); (*) }};
                                       result
                               main
```

Notes

- main has no argument or local variables and its result is "never" used; its AR is uninteresting
- (*) and (**) are return addresses of the invocations of f
 - The return address is where execution resumes after a procedure call finishes
- This is only one of many possible AR designs
 - Would also work for C, Pascal, FORTRAN, etc.

The Main Point

The compiler must determine, at compiletime, the layout of activation records and generate code that, when executed at runtime, correctly accesses locations in those activation records.

Thus, the AR layout and the compiler must be designed together!

Discussion

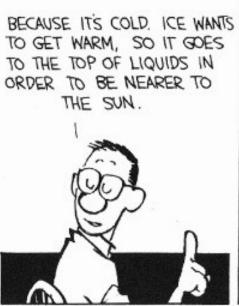
- The advantage of placing the return value 1st in a frame is that the caller can find it at a fixed offset from its own frame
 - The caller must write the return address there

- There is nothing magic about this organization
 - Can rearrange order of frame elements
 - Can divide caller/callee responsibilities differently
 - An organization is better if it improves execution speed or simplifies code generation
 - Ask me about what embedded devices do.

Discussion (Cont.)

- Real compilers hold as much of the frame as possible in registers
 - Especially the method result and arguments
- Why?









Globals

- All references to a global variable point to the same object
 - Can't store a global in an activation record
 - Is this true?

- Globals are assigned a fixed address once
 - Variables with fixed address are "statically allocated"
- Depending on the language, there may be other statically allocated values

Memory Layout with Static Data

Low Address Code Memory Static Data Stack High Address

Heap Storage

 A value that outlives the procedure that creates it cannot be kept in the AR

method foo() { new Bar }

The Bar value must survive deallocation of foo's AR

 Languages with dynamically allocated data use a heap to store dynamic data

Notes

- The code area contains object code
 - For most languages, fixed size and read only
- The static area contains data (not code) with fixed addresses (e.g., global data)
 - Fixed size, may be readable or writable
- The stack contains an AR for each currently active procedure
 - Each AR usually fixed size, contains locals
- Heap contains all other data
 - In C, heap is managed by *malloc* and *free*

Notes (Cont.)

- Both the heap and the stack grow
- Compilers must take care that they don't grow into each other
- Solution: start heap and stack at opposite ends of memory and let the grow towards

each other

Memory Layout with Heap

Low Address Code Memory Static Data Heap High Address Stack

Your Own Heap

We must emit assembly code for things like:

```
let x = new Counter(5) in
let y = x in {
    x.increment(1);
    print( y.getCount() ); // what does this print?
}
```

 You'll need to use and manage explicit heap (as described today and also next week). A heap maps addresses (integers) to values.

Homework

- PA4 checkpoint due!
- PA4 due in one week
- WA4 due Wednesday