

**Electrical Engineering and Computer Science** EECS373 - Design of Microprocessor-Based Systems

# Wizard's Chess

Trey Grunnagle, Lisa Herta, Lizzie Paris {tgrunn, hertal, elizpar}@umich.edu

# Introduction: Hand's Free Chess: The Idea and Basic Implementation

## **Idea:**

- Bring to action a scaled down version of the chess played in 'Harry Potter and the Sorcerer's Stone'
- Try to make chess a hands-free endeavor Implementation:



- Make an Android app to text which piece you would like to move and where, checks validity of submitted move
- Use magnets under the pieces and set in motion by stepper motors
- Use servo motor to magnetically glide pieces across board

# Problem Description: Putting an Interesting Spin on an Old Classic

- We wanted to put a fun spin on a ulletclassic board game by combining new and old technologies
- Use magnets and motors, along with ulletan Android platform as part of an effort to mimic a "magic" effect



# Solution:

## Human Interface

#### The Go-Between

## The Board and Pieces









- **Serial Bluetooth Device** 
  - **Communicates with app running on Android**
  - Sends and receives 'move' messages
- The App
  - Back End
    - Maintains state of game

- **ARM Cortex-M3** 
  - Serial communication with BlueSmirf
  - Software PWM generated by timer interrupts for precise control of stepper motors
  - Hardware PWM to control servo motor angle
  - **GPIO** for motor direction control
- EasyDriver Stepper Motor Controller
- The Chess Board
  - Made from an old unused scanner
- The Piece Selection
  - Servo arm rotates by PWM ,uses attached magnet to engage/disengage chess pieces

Parses user input

Conclusion

- Checks legality of moves
- Communicates move to embedded system
- **Front End** 
  - Includes simple move history
  - **Graphical representation of chess game**
- One driver for each motor takes a PWM signal and 0-3.3V for motor direction
- The X-Y Motion
  - X-direction uses scanner bed stepper motor and gear system
  - Y-direction uses a standalone stepper motor and threaded rod to propel servo motor block
- The Pieces
- Inexpensive travel set pieces, cut down to fit board limitations
- Underside has rare earth magnetic discs

By starting with serial communications from an Android App, we were able to accept messages from the device as fabric interrupts to the system. Then we used timers, along with pulse width modulated signals and manipulation of duty cycles to control servo and stepper motors which allow us complete control of XY movement and engagement of pieces when paired with magnets to implement our vision of 'Wizard's Chess'.