# EECS 442 Discussion 5

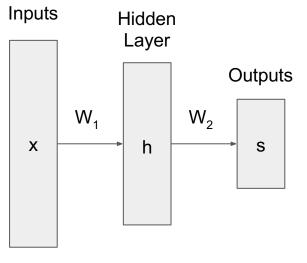
Backpropagation

## **Discussion Agenda**

- Neural Network
- Layers
  - Fully Connected
  - ReLU
- Computational Graphs
  - Forward and Backward Passes
  - Chain Rule
- Backpropagation
- Optimizer
  - SGD with Momentum

#### **Neural Networks**

• Models that can learn varying features of data by approximating *almost any* nonlinear function

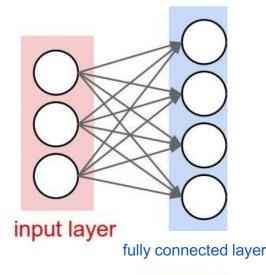


 $f(x) = W_2 h(W_1 x + b_1) + b_2$ 

### Fully Connected Layer

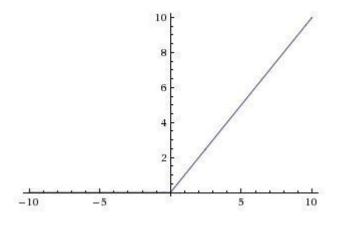
For regular neural networks, the most common layer type is the fully-connected layer in which neurons between two adjacent layers are fully pairwise connected, but neurons within a single layer share no connections.

The weight dimension is (3, 4) in the right example.

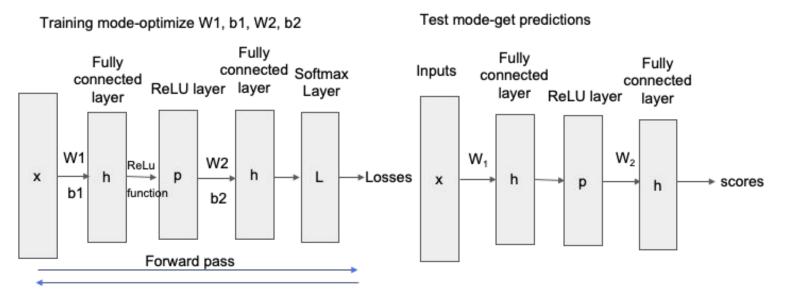


## Rectified Linear Unit (ReLU)

- Activation function: introduces non-linearity
- Thresholded at zero
- f(x) = max(0, x)
- Accelerates the convergence of Stochastic Gradient Descent (SGD)
- Simple to implement and fast to compute



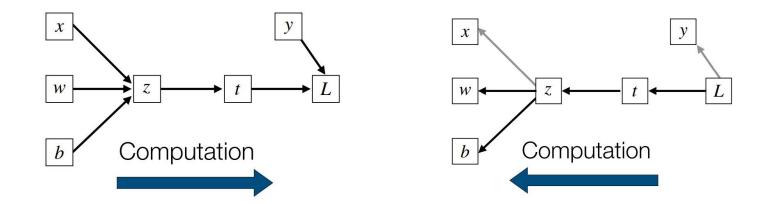
#### **Network Structure for PS4**



Backward pass, try to find grad\_W1, grad\_b1, grad\_W2, grad\_b2

### **Computational Graphs**

- Computing gradients is infeasible for complex models
  - Need to analytically derive all gradients
- Instead: modularize computation!

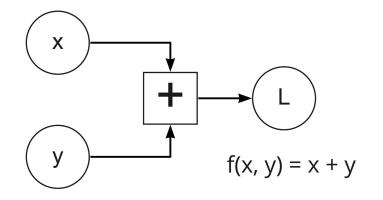


#### Forward and Backward Passes

$$f(x,y) = x + y$$

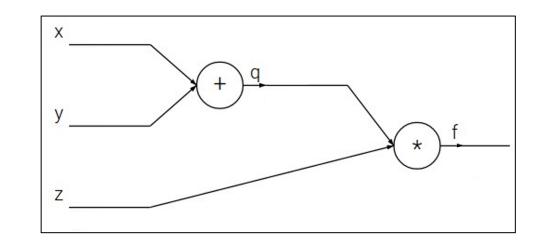
1. Forward pass: Compute outputs

L = x + y

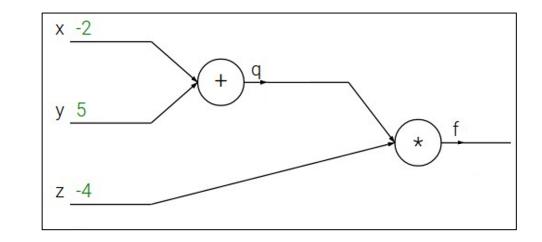


$$rac{\partial f}{\partial y} = 1 \quad rac{\partial f}{\partial x} = 1$$

$$f(x, y, z) = (x + y) \cdot z$$



$$f(x, y, z) = (x + y) \cdot z$$
  
e.g. x = -2, y = 5, z = -4

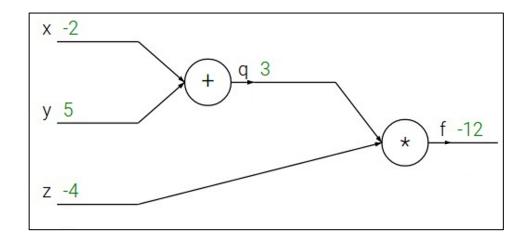


$$f(x, y, z) = (x + y) \cdot z$$
  
e.g. x = -2, y = 5, z = -4

1. Forward pass: Compute outputs

$$q = x + y \quad f = q \cdot z$$

Want: 
$$\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}$$

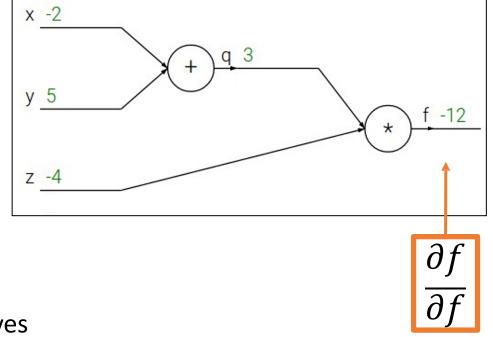


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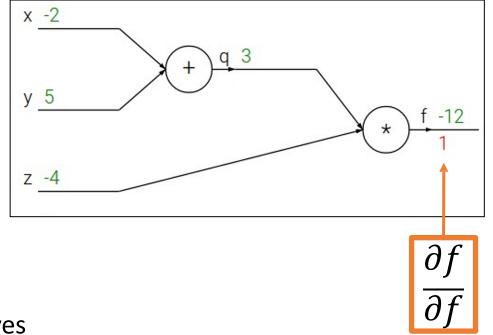


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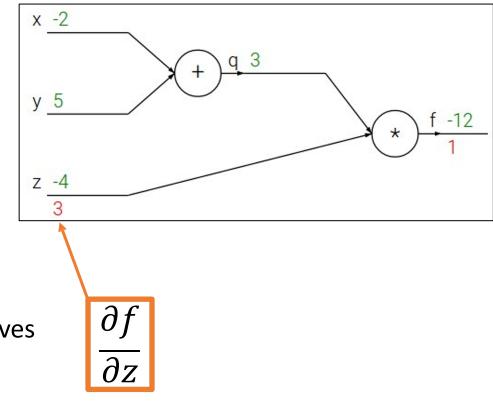


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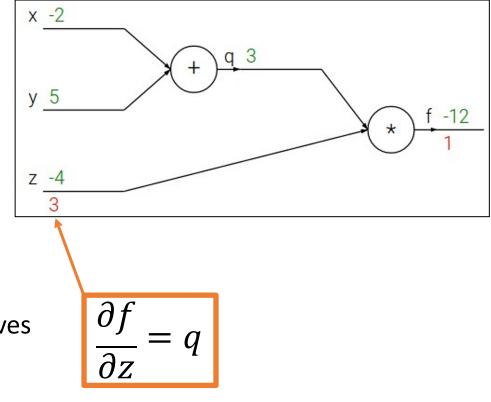
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$$f(x, y, z) = (x + y) \cdot z$$
  
e.g. x = -2, y = 5, z = -4

**1. Forward pass**: Compute outputs a = x + v  $f = a \cdot z$ 

Want: 
$$\frac{\partial f}{\partial y}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}$$

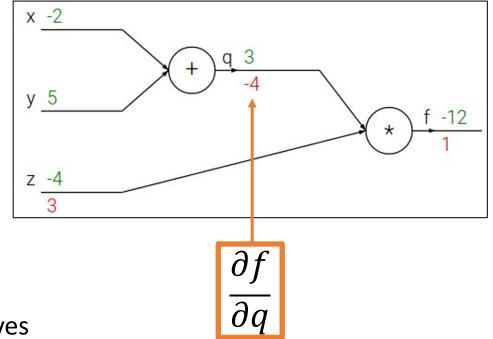


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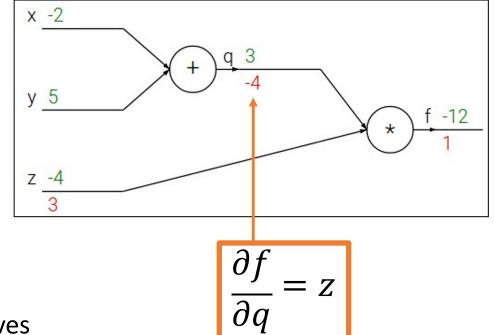


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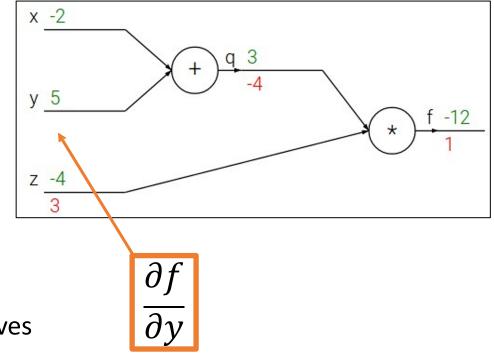


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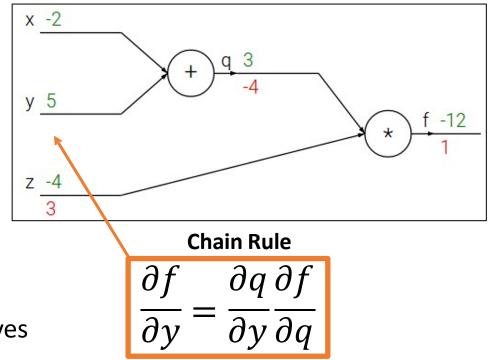


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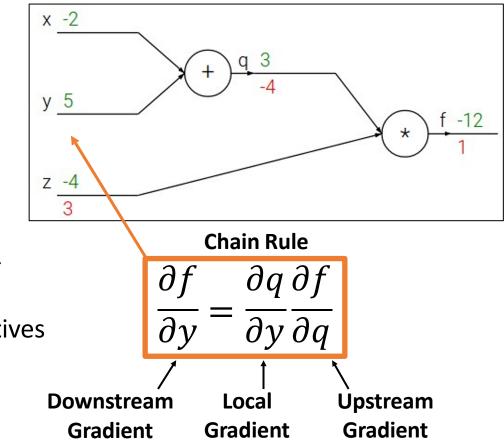
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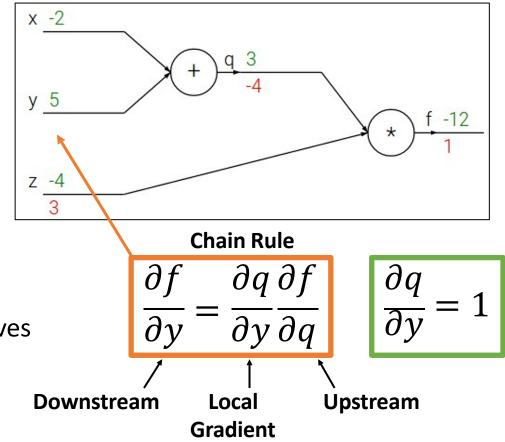
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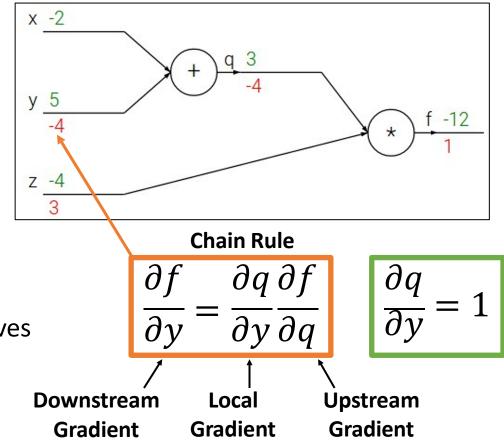
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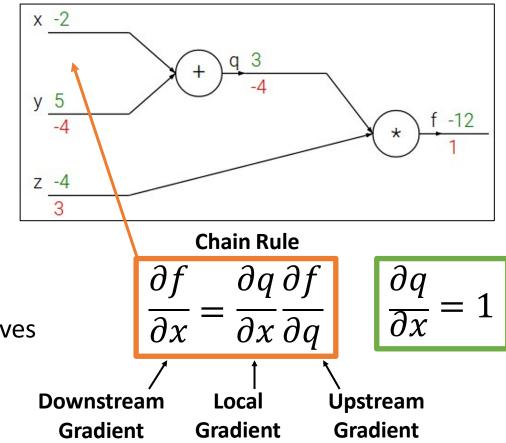
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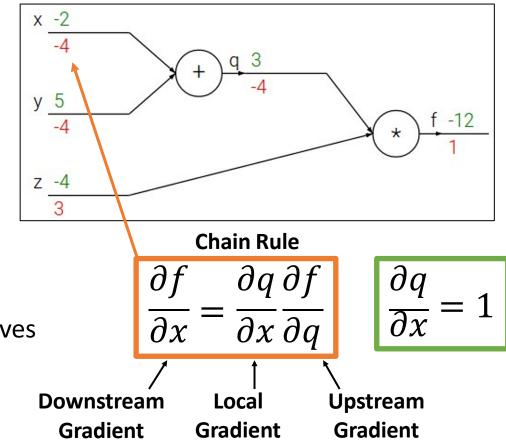
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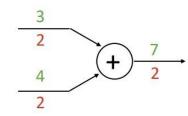
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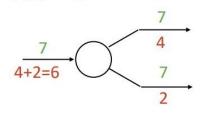


#### Backpropagation of some common operations

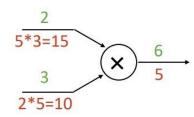
#### add gate: gradient distributor



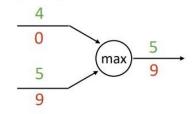
copy gate: gradient adder



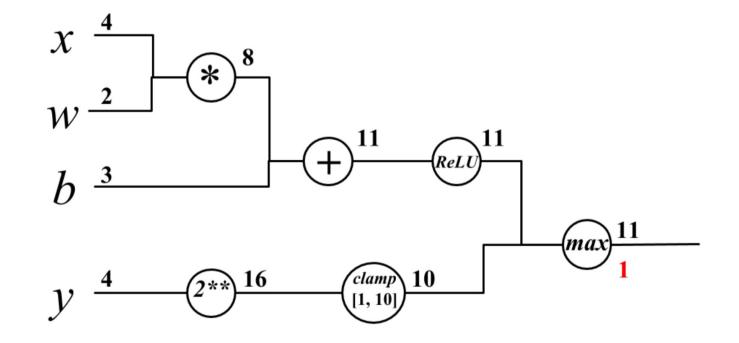
#### mul gate: "swap multiplier"



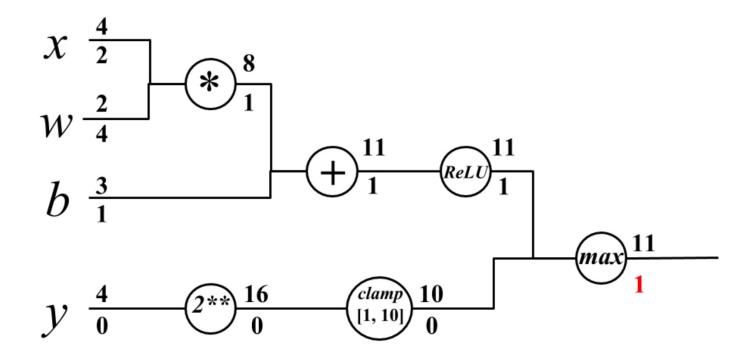
max gate: gradient router



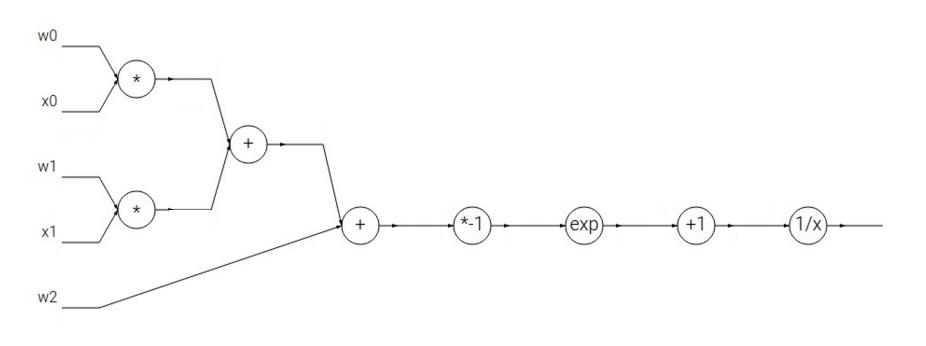
#### Practice 1

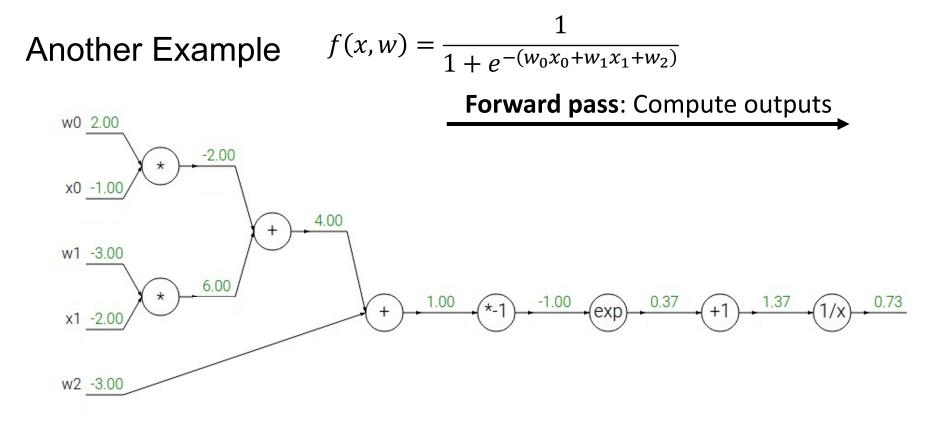


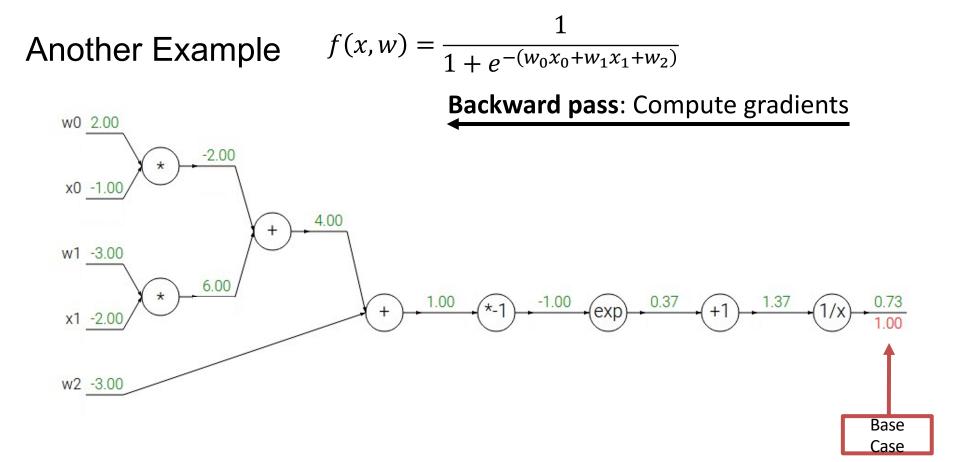
#### Practice 1

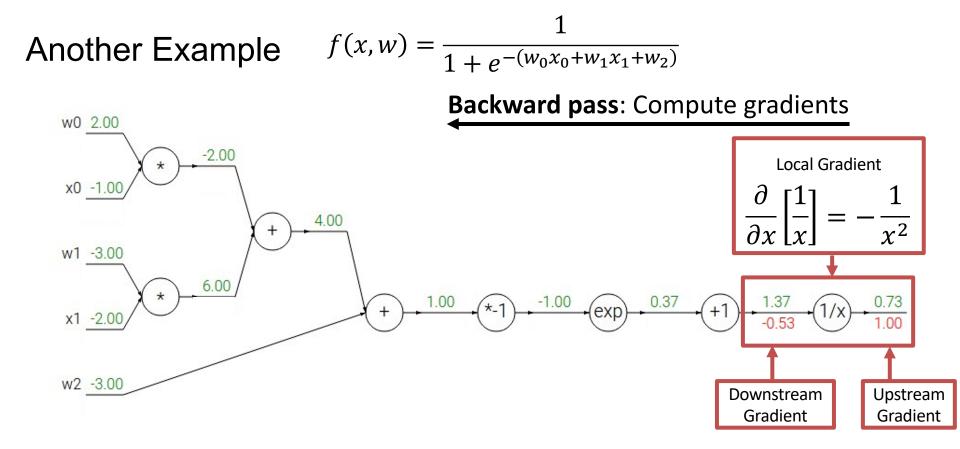


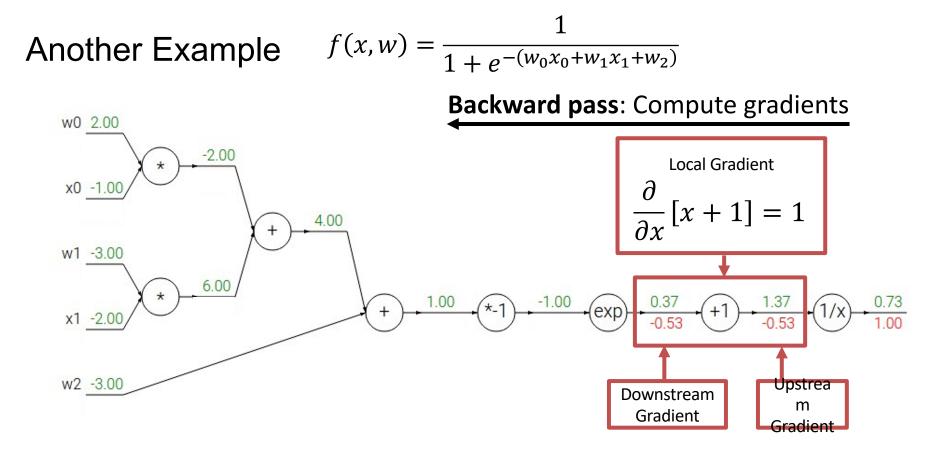
# Another Example $f(x, w) = \frac{1}{1 + e^{-(w_0 x_0 + w_1 x_1 + w_2)}}$

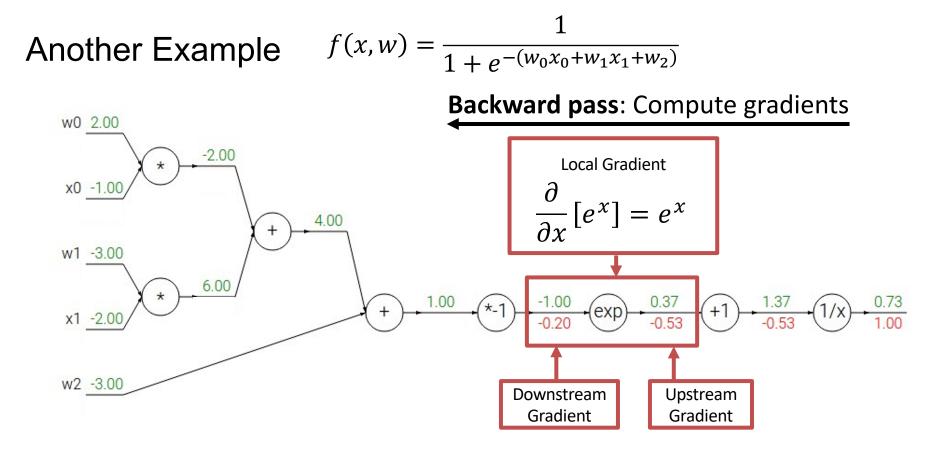


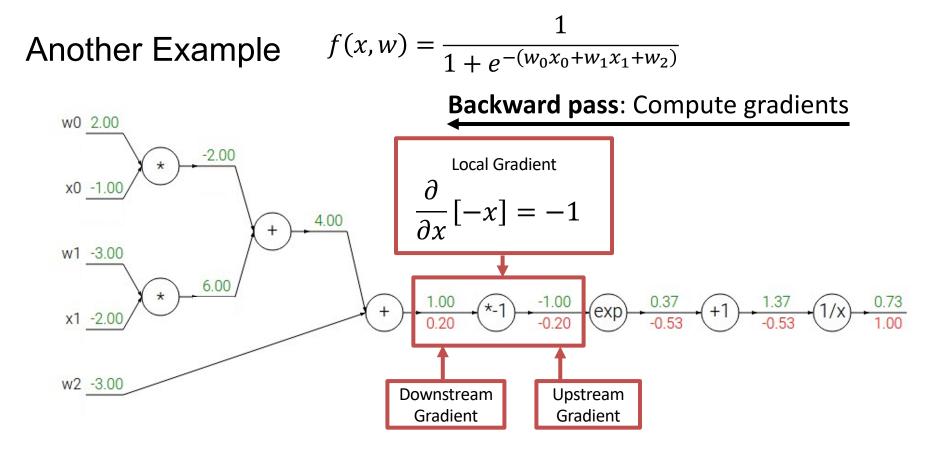


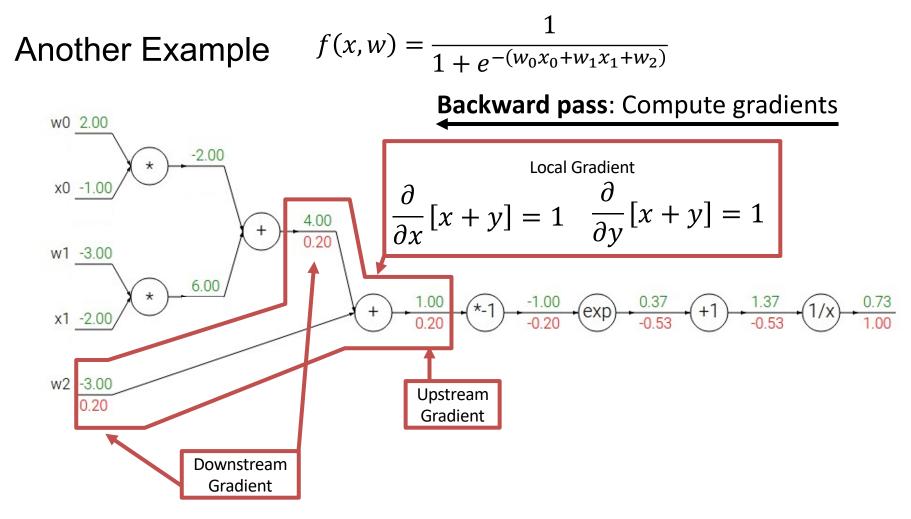


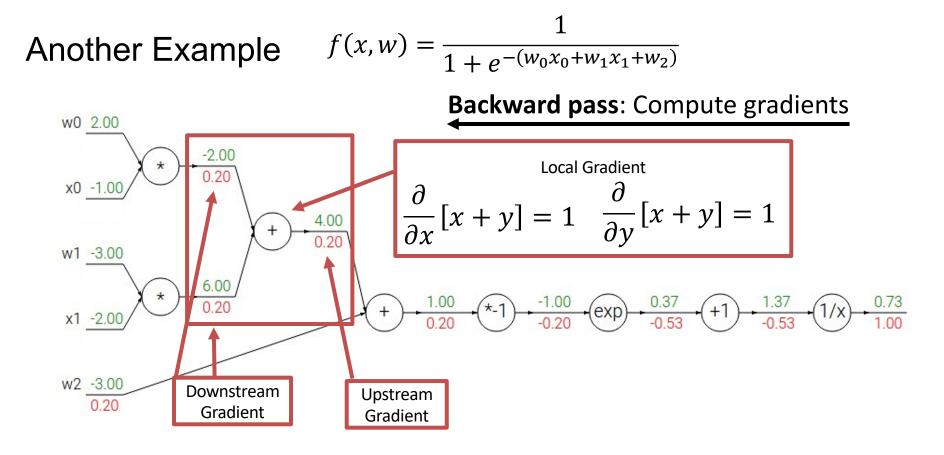


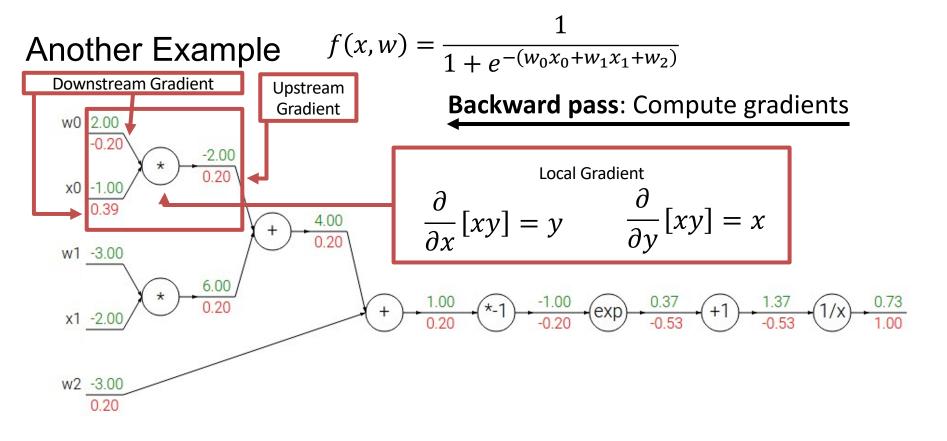


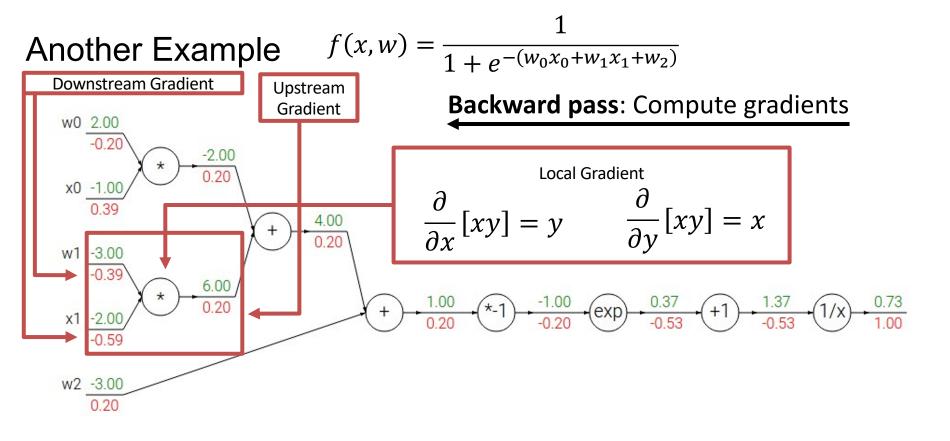










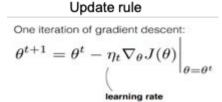


### SGD + Momentum

Stochastic Gradient Descent

Select training samples instead of looping over all training examples

$$\nabla J(\theta) \approx \frac{1}{|B|} \sum_{i \in B} \nabla L(x_i, y_i, \theta)$$



where B is a minibatch: a random subset of examples

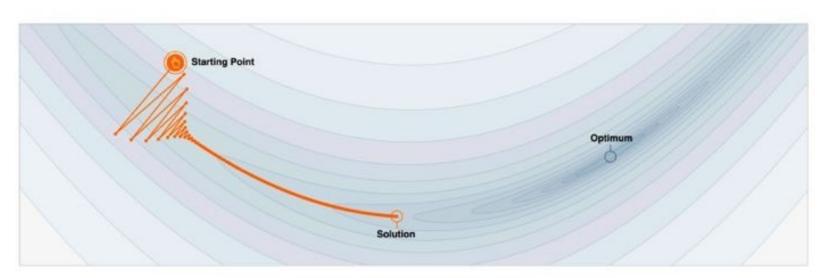
#### Momentum

SGD with Momentum has the following update rule

 $\begin{array}{l} v \leftarrow dW + \beta * v \\ W \leftarrow W - \text{learning\_rate} * v \end{array}$ 

where beta is a scalar in range [0,1], dW is the gradient of the network parameter W, v is velocity initialized as all zeros.

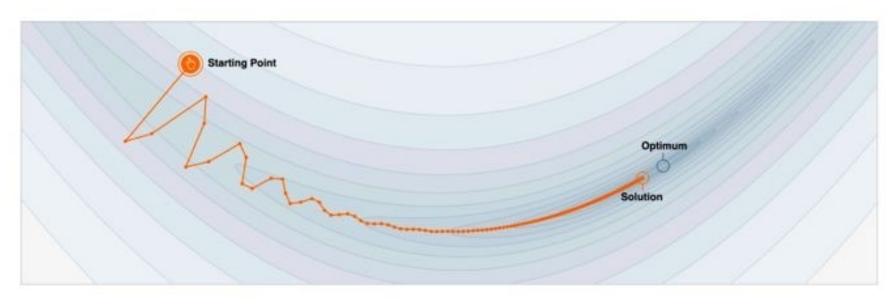
#### No Momentum



 $\beta = 0$  i.e. disable momentum

Source: https://distill.pub/2017/momentum

#### With Momentum



 $\beta = 0.99$